

Affine hemispheres of elliptic type

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Abstract

We find that for any n -dimensional, compact, convex set $K \subseteq \mathbb{R}^{n+1}$ there is an affinely-spherical hypersurface $M \subseteq \mathbb{R}^{n+1}$ with center at the relative interior of K , such that the disjoint union $M \cup K$ is the boundary of an $(n+1)$ -dimensional, compact, convex set. This so-called affine hemisphere M is uniquely determined by K up to affine transformations, it is of elliptic type, is associated with K in an affinely-invariant manner, and it is centered at the Santaló point of K .

1 Introduction

Let $M \subseteq \mathbb{R}^{n+1}$ be a smooth, connected hypersurface which is locally strongly-convex, i.e., the second fundamental form is a definite symmetric bilinear form at any point $y \in M$. There are several ways to define the affine normal line $\ell_M(y)$ at a point $y \in M$. One possibility is to define $\ell_M(y)$ via the following procedure:

- (i) Let $H = T_y M$ be the tangent space to M at the point $y \in M$, viewed as a linear subspace of codimension one in \mathbb{R}^{n+1} . Select a vector $v \notin H$ pointing to the convex side of M at the point $y \in M$, and denote $M_t = M \cap (H + tv)$ for $t > 0$. Here, $H + tv = \{x + tv; x \in H\}$.
- (ii) For a sufficiently small $t > 0$, the section M_t encloses an n -dimensional convex body $\Omega_t \subseteq H + tv$. The barycenters $b_t = \text{bar}(\Omega_t)$ depend smoothly on t . The affine normal line $\ell_M(y) \subseteq \mathbb{R}^{n+1}$ is defined to be the line passing through y in the direction of the non-zero vector $\frac{d}{dt}b_t|_{t=0}$.

We say that M is *affinely-spherical* with center at a point $p \in \mathbb{R}^{n+1}$ if all of the affine normal lines of M meet at p . In the case where all of the affine normal lines are parallel, we say that M is affinely-spherical with center at infinity. An *affine sphere* is an affinely-spherical hypersurface which is *complete*, i.e., it is a closed subset of \mathbb{R}^{n+1} . This definition is clearly affinely-invariant, hence the term “affine sphere”. In Section 5 below we explain that M is affinely-spherical with center at the origin if and only if the cone measure on M is mapped to a measure proportional to the cone measure on the polar hypersurface M^* via the polarity map.

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Affine spheres were introduced by the Romanian geometer Tzitzéica [24, 25]. All convex quadratic hypersurfaces in \mathbb{R}^{n+1} are affine spheres, as well as the hypersurface

$$M = \left\{ (x_1, \dots, x_n) \in \mathbb{R}^n; \forall i, x_i > 0, \prod_{i=1}^n x_i = 1 \right\},$$

found by Tzitzéica [24, 25] and Calabi [10]. See Loftin [18] for a survey on affine spheres. At any point $y \in M$, the punctured line $\ell_M(y) \setminus \{y\}$ is naturally divided into two rays: one pointing to the convex side of M and the other to the concave side. These two rays are referred to as the convex side and the concave side of $\ell_M(y)$, respectively. An affinely-spherical hypersurface M is called *elliptic* if its center lies on the convex side of all of the affine normal lines. It is *hyperbolic* if its center lies on the concave side of all of the affine normal lines. There are also parabolic affine spheres, whose affine normal lines are all parallel.

Ellipsoids in \mathbb{R}^{n+1} are elliptic affine spheres, while elliptic paraboloids are parabolic affine spheres. There are no other examples of complete affine spheres of elliptic or parabolic type. This non-trivial theorem is the culmination of the works of Blaschke [4], Calabi [9], Pogorelov [21] and Trudinger and Wang [23].

While affine spheres of elliptic or parabolic type are quite rare, there are many hyperbolic affine spheres in \mathbb{R}^{n+1} . From the works of Calabi [10] and Cheng-Yau [11] we learn that for any non-empty, open, convex cone $C \subseteq \mathbb{R}^{n+1}$ that does not contain a full line, there exists a hyperbolic affine sphere which is asymptotic to the cone. This hyperbolic affine sphere is determined by the cone C up to homothety, and all hyperbolic affine spheres in \mathbb{R}^{n+1} arise this way. Why are there so few elliptic affine spheres, compared to the abundance of hyperbolic affine spheres? Perhaps completeness is too strong a requirement in the elliptic case. We propose the following:

Definition 1.1. *Let $M \subseteq \mathbb{R}^{n+1}$ be a smooth, connected, locally strongly-convex hypersurface. We say that M is an “affine hemisphere” if*

1. *There exist compact, convex sets $K, \tilde{K} \subseteq \mathbb{R}^{n+1}$, with $\dim(K) = n$ and $\dim(\tilde{K}) = n + 1$, such that M does not intersect the affine hyperplane spanned by K and*

$$K \cup M = \partial \tilde{K}.$$

2. *The hypersurface M is affinely-spherical with center at the relative interior of K .*

We say that K is the “anchor” of the affine hemisphere M .

In Definition 1.1, the dimension $\dim(K)$ is the maximal number N such that K contains $N + 1$ affinely-independent vectors. Note that when $M \subseteq \mathbb{R}^{n+1}$ is an affine hemisphere, its anchor K is the compact, convex set enclosed by $\overline{M} \setminus M$, where \overline{M} is the closure of M . In particular, $K = \text{Conv}(\overline{M} \setminus M)$ where Conv denotes convex hull. It is clear that an affine hemisphere is always of elliptic type.

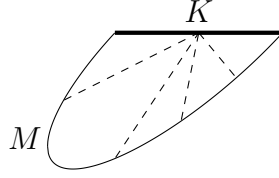


Figure 1: Half of an ellipse, which is an affine one-dimensional hemisphere in \mathbb{R}^2 .

Theorem 1.2. *Let $K \subseteq \mathbb{R}^{n+1}$ be an n -dimensional, compact, convex set. Then there exists an affine hemisphere $M \subseteq \mathbb{R}^{n+1}$ with anchor K , uniquely determined up to affine transformations. The affine hemisphere M is centered at the Santaló point of K .*

Thus, with any n -dimensional, compact, convex set $K \subseteq \mathbb{R}^{n+1}$ we associate an $(n + 1)$ -dimensional, compact, convex set $\tilde{K} \subseteq \mathbb{R}^{n+1}$ whose boundary consists of two parts: the convex set K itself is a facet, and the rest of the boundary is an affine hemisphere M centered at the Santaló point of K . We refer the reader to Loftin [18] and to Nomizu and Sasaki [20] for information about the rich geometric structure associated with affinely-spherical hypersurfaces. Let us just observe here that by [20, Theorem 6.5], any affine function in \mathbb{R}^{n+1} that vanishes on K is an eigenfunction of the affine-metric Laplacian of M with Dirichlet boundary conditions, corresponding to the first eigenvalue.

The proof of Theorem 1.2 is basically a variant of the *moment measure* construction by Cordero-Erausquin and the author [12] which is in turn influenced by Berman and Berndtsson [3] and is also analogous to the classical Minkowski problem. Let us now present a few questions about affine hemispheres:

1. Other than half-ellipsoids, we are not aware of any affine hemisphere that may be described by a simple formula. Is there a closed form for the affine hemisphere associated with the n -dimensional simplex or the n -dimensional cube? For moment measures, the solutions in the case of the simplex and the cube are given by explicit formulæ, see [12].
2. Calabi [10] found a composition rule for hyperbolic affine spheres, allowing one to construct a hyperbolic affine sphere of dimension $n+m+1$ from two hyperbolic affine spheres of dimensions n and m . Is there an analogous construction for affine hemispheres?
3. An intriguing question is whether an affine hemisphere M can be extended beyond its anchor K , to an affinely-spherical hypersurface $\tilde{M} \supsetneq M$. When the anchor K is an ellipsoid, the affine hemisphere M with anchor K is half an ellipsoid, and may clearly be extended to the surface of a full ellipsoid. On the other hand, if K is a polytope, then the affine hemisphere M cannot be smoothly extended beyond the vertices of K .
4. Finally, is there a theory similar to that of affine hemispheres that is related to *parabolic* affinely-spherical hypersurfaces? See Ferrer, Martínez and Milán [14], Milán [19] and Remark 5.12 below for partial results in this direction.

Throughout this paper, by smooth we always mean C^∞ -smooth. We write $|\cdot|$ for the usual Euclidean norm in \mathbb{R}^n , and $S^n = \{x \in \mathbb{R}^{n+1}; |x| = 1\}$ is the Euclidean unit sphere centered at the origin. The standard scalar product of $x, y \in \mathbb{R}^n$ is denoted by $\langle x, y \rangle$. We write \log for the natural logarithm. For a Borel measure μ in \mathbb{R}^n we denote by $\text{Supp}(\mu)$ the support of μ , which is the intersection of all closed sets of a full μ -measure. A hypersurface in \mathbb{R}^{n+1} is an n -dimensional submanifold of \mathbb{R}^{n+1} . A submanifold $M \subseteq \mathbb{R}^{n+1}$ *encloses* a convex set $K \subseteq \mathbb{R}^{n+1}$ if M is the boundary of K relative to the affine subspace spanned by K .

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2 A variational problem

In this section we analyze a variational problem related to affine hemispheres. Similar variational problems were considered by Berman and Berndtsson [3] and by Cordero-Erausquin and the author [12]. For a function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ denote

$$\text{Dom}(\psi) = \{x \in \mathbb{R}^n; \psi(x) < +\infty\}.$$

The Legendre transform of ψ is the convex function

$$\psi^*(y) = \sup_{x \in \text{Dom}(\psi)} [\langle x, y \rangle - \psi(x)] \quad (y \in \mathbb{R}^n),$$

where $\sup \emptyset = -\infty$. The function ψ^* is always convex and lower semi-continuous. A convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is *proper* if it is lower semi-continuous with $\text{Dom}(\psi) \neq \emptyset$. When ψ is convex and proper, the Legendre transform ψ^* is again convex and proper, and $\psi^{**} = \psi$. We will frequently use the formula $\psi^*(0) = -\inf \psi$, as well as the relation $(\lambda\psi)^*(x) = \lambda\psi^*(x/\lambda)$, which is valid for any $x \in \mathbb{R}^n$ and $\lambda > 0$. It is also well-known that for any $v \in \mathbb{R}^n$, denoting $\psi_1(x) = \psi(x) + \langle x, v \rangle$,

$$\psi_1^*(y) = \psi^*(y - v) \quad (y \in \mathbb{R}^n). \quad (1)$$

See Rockafellar [26] for a thorough discussion of the Legendre transform. For $p > 0$ and a function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$ we define

$$\mathcal{I}_p(\psi) = \left(\int_{\mathbb{R}^n} \frac{dx}{(\psi^*(x))^{n+p}} \right)^{-1/p} \in [0, +\infty]. \quad (2)$$

Two remarks are in order: First, note that $\inf \psi^* \geq -\psi(0) > 0$, and that the integral in (2) is a well-defined element of $[0, +\infty]$. Second, for the purpose of definition (2) let us agree that $0^{-\alpha} = +\infty$ and $(+\infty)^{-\alpha} = 0$ for $\alpha > 0$. The functional \mathcal{I}_p is closely related to the Borell-Brascamp-Lieb inequality [5, 6]. The latter inequality, which is a variant of Brunn-Minkowski,

states the following: For any $0 < \lambda < 1$ and three convex functions $\varphi_\lambda, \varphi_0, \varphi_1 : \mathbb{R}^n \rightarrow (0, +\infty]$ such that

$$\varphi_\lambda((1-\lambda)x + \lambda y) \leq (1-\lambda)\varphi_0(x) + \lambda\varphi_1(y) \quad (x, y \in \mathbb{R}^n), \quad (3)$$

we have,

$$\left(\int_{\mathbb{R}^n} \frac{dx}{\varphi_\lambda(x)^{n+p}} \right)^{-1/p} \leq (1-\lambda) \left(\int_{\mathbb{R}^n} \frac{dx}{\varphi_0(x)^{n+p}} \right)^{-1/p} + \lambda \left(\int_{\mathbb{R}^n} \frac{dx}{\varphi_1(x)^{n+p}} \right)^{-1/p}. \quad (4)$$

The Borell-Brascamp-Lieb inequality, sometimes called the dimensional Prékopa inequality, implies the convexity of \mathcal{I}_p as is stated in the following:

Lemma 2.1. *Let $p, \lambda > 0$, and let $\psi, \psi_0, \psi_1 : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be functions that are negative at zero. Denote $\varphi = \psi^*, \varphi_0 = \psi_0^*$ and $\varphi_1 = \psi_1^*$. Then the following hold:*

- (i) $\mathcal{I}_p(\lambda\psi) = \lambda\mathcal{I}_p(\psi)$.
- (ii) $\mathcal{I}_p(\psi_0 + \psi_1) \leq \mathcal{I}_p(\psi_0) + \mathcal{I}_p(\psi_1)$.
- (iii) *Assume that $\text{Dom}(\varphi_0) = \text{Dom}(\varphi_1) = \mathbb{R}^n$. Then equality in (ii) holds if and only if there exist $x_0 \in \mathbb{R}^n$ and $\lambda > 0$ such that*

$$\varphi_1(x) = \lambda\varphi_0(x_0 + x/\lambda) \quad \text{for all } x \in \mathbb{R}^n.$$

Proof. By using the formula $(\lambda\psi)^*(x) = \lambda\varphi(x/\lambda)$, which is valid for any $x \in \mathbb{R}^n$, we obtain

$$\mathcal{I}_p(\lambda\psi) = \left(\int_{\mathbb{R}^n} \frac{dx}{(\lambda\varphi(x/\lambda))^{n+p}} \right)^{-1/p} = \lambda^{\frac{n+p}{p}} \cdot \lambda^{-\frac{n}{p}} \left(\int_{\mathbb{R}^n} \frac{dx}{\varphi(x)^{n+p}} \right)^{-1/p} = \lambda\mathcal{I}_p(\psi).$$

Thus (i) is proven. Next, denote $\varphi_{1/2} = [(\psi_0 + \psi_1)/2]^*$. Then $\varphi_0, \varphi_1, \varphi_{1/2} : \mathbb{R}^n \rightarrow (0, +\infty]$ are convex functions, and for any $x, y \in \mathbb{R}^n$,

$$\begin{aligned} \varphi_{1/2}\left(\frac{x+y}{2}\right) &= \sup_{z \in \text{Dom}(\psi_0) \cap \text{Dom}(\psi_1)} \left[\left\langle \frac{x+y}{2}, z \right\rangle - \frac{\psi_0(z) + \psi_1(z)}{2} \right] \\ &\leq \frac{1}{2} \left\{ \sup_{z \in \text{Dom}(\psi_0)} [\langle x, z \rangle - \psi_0(z)] + \sup_{z \in \text{Dom}(\psi_1)} [\langle y, z \rangle - \psi_1(z)] \right\} = \frac{\varphi_0(x) + \varphi_1(y)}{2}. \end{aligned}$$

Hence condition (3) is satisfied, with $\lambda = 1/2$. The case $\lambda = 1/2$ of the Borell-Brascamp-Lieb inequality (4) implies that

$$\mathcal{I}_p\left(\frac{\psi_0 + \psi_1}{2}\right) \leq \frac{\mathcal{I}_p(\psi_0) + \mathcal{I}_p(\psi_1)}{2}$$

and (ii) now follows from (i). According to Dubuc [13], equality holds in (4), with $\varphi_0, \varphi_1 : \mathbb{R}^n \rightarrow (0, +\infty)$ being convex functions, if and only if there exist $\lambda > 0$ and $x_0 \in \mathbb{R}^n$ such that $\varphi_1(x) = \lambda\varphi_0(x_0 + x/\lambda)$ for all $x \in \mathbb{R}^n$. This proves (iii). \square

The next lemma describes a lower semi-continuity property of the functional \mathcal{I}_p .

Lemma 2.2. *Let $p > 0$ and let $K \subseteq \mathbb{R}^n$ be a convex, open set containing the origin. Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a convex function with $\psi(0) < 0$ such that $K \subseteq \text{Dom}(\psi) \subseteq \overline{K}$. Assume that for any $\ell \geq 1$ we are given a function $\psi_\ell : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi_\ell(0) < 0$, such that $\psi_\ell \rightarrow \psi$ pointwise in the set K as $\ell \rightarrow \infty$. Then,*

$$\mathcal{I}_p(\psi) \leq \liminf_{\ell \rightarrow \infty} \mathcal{I}_p(\psi_\ell).$$

Proof. The convex function ψ is finite and hence continuous in the convex, open set K . Since $0 \in K$ and $\psi(0) < 0$, we may find $\varepsilon > 0$ and linearly independent vectors $v_1, \dots, v_n \in K$ such that

$$\psi(\pm v_i) < -\varepsilon \quad \text{for } i = 1, \dots, n.$$

By the pointwise convergence in K , there exists ℓ_0 such that $\psi_\ell(\pm v_i) < -\varepsilon$ for all $\ell \geq \ell_0$ and $i = 1, \dots, n$. The convex hull of the $2n$ points $\{\pm v_i; i = 1, \dots, n\}$ contains a Euclidean ball of radius $\delta > 0$ centered at the origin. Consequently, for $\ell \geq \ell_0$ and $x \in \mathbb{R}^n$,

$$\psi_\ell^*(x) = \sup_{y \in \text{Dom}(\psi_\ell)} [\langle x, y \rangle - \psi_\ell(y)] \geq \sup_{i=1, \dots, n} [|\langle x, v_i \rangle| + \varepsilon] \geq \varepsilon + \delta|x|. \quad (5)$$

Next, we claim that for any $x_0 \in \mathbb{R}^n$,

$$\psi^*(x_0) \leq \liminf_{\ell \rightarrow \infty} \psi_\ell^*(x_0). \quad (6)$$

Indeed, since ψ is convex, its restriction to any line segment in the convex set $\text{Dom}(\psi)$ is upper semi-continuous (see, e.g., [15]). From the inclusion $\text{Dom}(\psi) \subseteq \overline{K}$ we thus learn that

$$\psi^*(x_0) = \sup_{y \in \text{Dom}(\psi)} [\langle x_0, y \rangle - \psi(y)] = \sup_{y \in K} [\langle x_0, y \rangle - \psi(y)].$$

Hence, for any $\varepsilon > 0$ there exists $y_0 \in K$ such that $\psi^*(x_0) \leq \varepsilon + \langle x_0, y_0 \rangle - \psi(y_0)$. By the pointwise convergence in K , for a sufficiently large ℓ we observe that $\psi_\ell(y_0) \leq \psi(y_0) + \varepsilon$. Therefore, for a sufficiently large ℓ ,

$$\psi_\ell^*(x_0) \geq \langle x_0, y_0 \rangle - \psi_\ell(y_0) \geq -\varepsilon + \langle x_0, y_0 \rangle - \psi(y_0) \geq -2\varepsilon + \psi^*(x_0)$$

and (6) is proven. The function $(\varepsilon + \delta|x|)^{-(n+p)}$ is integrable in \mathbb{R}^n . Thanks to (5) and (6) we may use the dominated convergence theorem, and conclude that

$$\begin{aligned} \int_{\mathbb{R}^n} \frac{dx}{(\psi^*(x))^{n+p}} &\geq \int_{\mathbb{R}^n} \left[\limsup_{\ell \rightarrow \infty} \sup_{k \geq \ell} \frac{1}{(\psi_k^*(x))^{n+p}} \right] dx = \lim_{\ell \rightarrow \infty} \int_{\mathbb{R}^n} \left[\sup_{k \geq \ell} \frac{1}{(\psi_k^*(x))^{n+p}} \right] dx \\ &= \limsup_{\ell \rightarrow \infty} \int_{\mathbb{R}^n} \left[\sup_{k \geq \ell} \frac{1}{(\psi_k^*(x))^{n+p}} \right] dx \geq \limsup_{\ell \rightarrow \infty} \int_{\mathbb{R}^n} \frac{dx}{(\psi_\ell^*(x))^{n+p}}. \quad \square \end{aligned}$$

The next theorem is our main result in this section. It is essentially a theorem about the Legendre transform of the functional \mathcal{I}_p^2 , viewed as a convex functional on an infinite-dimensional cone.

Theorem 2.3. *Let $p > 0$ and let μ be a Borel probability measure on \mathbb{R}^n with $\int_{\mathbb{R}^n} |x| d\mu(x) < +\infty$ such that the barycenter of μ lies at the origin. Assume that the origin belongs to the interior of $\text{Conv}(\text{Supp}(\mu))$. Then there exists a μ -integrable, proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$ such that*

$$\int_{\mathbb{R}^n} \psi d\mu + \left(\int_{\mathbb{R}^n} \frac{dx}{(\psi^*(x))^{n+p}} \right)^{-2/p} \leq \int_{\mathbb{R}^n} \psi_1 d\mu + \left(\int_{\mathbb{R}^n} \frac{dx}{(\psi_1^*(x))^{n+p}} \right)^{-2/p} \quad (7)$$

for any μ -integrable, proper, convex function $\psi_1 : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi_1(0) < 0$. Moreover, the expression on the left-hand side of (7) is a finite, negative number, and $\psi(x) = +\infty$ for any $x \in \mathbb{R}^n \setminus \overline{K}$ where K is the interior of $\text{Conv}(\text{Supp}(\mu))$.

The remainder of this section is dedicated to the proof of Theorem 2.3. Let us fix a number $p > 0$ and a Borel probability measure μ satisfying the requirements of Theorem 2.3. For a μ -integrable, proper convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$ we denote

$$\mathcal{I}_{\mu,p}(\psi) = \int_{\mathbb{R}^n} \psi d\mu + \mathcal{I}_p^2(\psi) = \int_{\mathbb{R}^n} \psi d\mu + \left(\int_{\mathbb{R}^n} \frac{dx}{(\psi^*(x))^{n+p}} \right)^{-2/p}.$$

Since the barycenter of μ is at the origin, we learn from (1) that $\mathcal{I}_{\mu,p}(\psi) = \mathcal{I}_{\mu,p}(\psi_1)$ whenever $\psi_1(x) = \psi(x) + \langle x, v \rangle$ for some $v \in \mathbb{R}^n$. The first step in the proof of Theorem 2.3 is the following proposition:

Proposition 2.4. *Let $p > 0$ and let μ be as in Theorem 2.3. Then,*

$$\inf_{\psi} \mathcal{I}_{\mu,p}(\psi) > -\infty$$

where the infimum runs over all μ -integrable, proper convex functions $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$.

The proof of Proposition 2.4 relies on several lemmas.

Lemma 2.5. *There exist $c_1, c_2 > 0$, depending on μ , with the following property: For any $\theta \in S^{n-1}$,*

$$\int_{\mathbb{R}^n} \langle x, \theta \rangle 1_{\{\langle x, \theta \rangle > c_1\}} d\mu(x) \geq c_2,$$

where $1_{\{\langle x, \theta \rangle > c_1\}}$ equals one when $\langle x, \theta \rangle > c_1$ and it vanishes elsewhere.

Proof. The origin belongs to the interior of $\text{Conv}(\text{Supp}(\mu))$. Therefore, for any $\theta \in S^{n-1}$,

$$\int_{\mathbb{R}^n} \langle x, \theta \rangle 1_{\{\langle x, \theta \rangle > 0\}} d\mu(x) > 0. \quad (8)$$

For $t > 0$ consider the non-negative function

$$f_t(\theta) = \int_{\mathbb{R}^n} \langle x, \theta \rangle 1_{\{\langle x, \theta \rangle > t\}} d\mu(x) \quad (\theta \in S^{n-1}).$$

We claim that f_t is lower semi-continuous. Indeed, if $\theta_j \rightarrow \theta$ then by Fatou's lemma,

$$f_t(\theta) = \int_{\mathbb{R}^n} \langle x, \theta \rangle 1_{\{\langle x, \theta \rangle > t\}} d\mu(x) \leq \liminf_{j \rightarrow \infty} \int_{\mathbb{R}^n} \langle x, \theta_j \rangle 1_{\{\langle x, \theta_j \rangle > t\}} d\mu(x) = \liminf_{j \rightarrow \infty} f_t(\theta_j).$$

Denote by m_t the minimum of the function f_t on S^{n-1} , and let $\theta_t \in S^{n-1}$ be a point such that $f_t(\theta_t) = m_t$. Since S^{n-1} is compact, there exists a sequence $t_j \rightarrow 0^+$ such that $\theta_{t_j} \rightarrow \theta$ for a certain unit vector $\theta \in S^{n-1}$. By (8) and Fatou's lemma,

$$0 < \int_{\mathbb{R}^n} \langle x, \theta \rangle 1_{\{\langle x, \theta \rangle > 0\}} d\mu(x) \leq \liminf_{j \rightarrow \infty} \int_{\mathbb{R}^n} \langle x, \theta_{t_j} \rangle 1_{\{\langle x, \theta_{t_j} \rangle > t_j\}} d\mu(x) = \liminf_{j \rightarrow \infty} m_{t_j}.$$

Consequently there exists $j \geq 1$ such that $m_{t_j} > 0$. The lemma follows with $c_1 = t_j$ and $c_2 = m_{t_j}$. \square

Lemma 2.6. *There exists $c > 0$, depending on μ , with the following property: Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a proper, convex function that is μ -integrable. Denote $\alpha = -\psi(0)$. Assume that $\psi(0) = \inf \psi$ and that $\int_{\mathbb{R}^n} \psi d\mu < 0$. Then for any $x \in \mathbb{R}^n$,*

$$\psi(x) \leq -\alpha/2 \quad \text{when } |x| < c.$$

Proof. We will prove the lemma with $c = \min\{c_1, c_2/4\}$ where c_1, c_2 are the positive constants from Lemma 2.5. Assume by contradiction that the conclusion of the lemma fails. Then the convex set $A = \{x \in \mathbb{R}^n; \psi(x) \leq -\alpha/2\}$ does not contain an open ball of radius c around the origin. By the convexity of A , there exists $\theta \in S^{n-1}$ such that $\langle x, \theta \rangle < c$ for all $x \in A$. By the convexity of the function ψ , for any $x \in \mathbb{R}^n$ with $\langle x, \theta \rangle \geq c$,

$$-\frac{\alpha}{2} < \psi\left(\frac{cx}{\langle x, \theta \rangle}\right) \leq \frac{c}{\langle x, \theta \rangle} \psi(x) + \left(1 - \frac{c}{\langle x, \theta \rangle}\right) \psi(0) = \frac{c}{\langle x, \theta \rangle} \psi(x) - \alpha \cdot \left(1 - \frac{c}{\langle x, \theta \rangle}\right).$$

Consequently, $\psi(x) \geq \alpha \langle x, \theta \rangle / (2c) - \alpha$ for any $x \in \mathbb{R}^n$ with $\langle x, \theta \rangle \geq c$. Since $\inf \psi = -\alpha$ and $c \leq c_1$, then by Lemma 2.5,

$$\begin{aligned} \int_{\mathbb{R}^n} \psi d\mu &= \int_{\mathbb{R}^n} \psi(x) 1_{\{\langle x, \theta \rangle \leq c_1\}} d\mu(x) + \int_{\mathbb{R}^n} \psi(x) 1_{\{\langle x, \theta \rangle > c_1\}} d\mu(x) \\ &\geq -\alpha + \int_{\mathbb{R}^n} \left[\frac{\alpha}{2c} \cdot \langle x, \theta \rangle - \alpha \right] \cdot 1_{\{\langle x, \theta \rangle > c_1\}} d\mu(x) \geq -2\alpha + \frac{\alpha}{2c} \cdot c_2 \geq -2\alpha + 2\alpha = 0, \end{aligned}$$

in contradiction to our assumption that $\int_{\mathbb{R}^n} \psi d\mu < 0$. \square

Lemma 2.7. *There exists $\tilde{c} > 0$, depending on μ and p , with the following property: Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a proper, convex function that is μ -integrable. Denote $\alpha = -\psi(0)$. Assume that $\psi(0) = \inf \psi$ and that $\int_{\mathbb{R}^n} \psi d\mu < 0$. Then,*

$$\mathcal{I}_{\mu,p}(\psi) \geq -\alpha + \tilde{c}\alpha^2.$$

Proof. From Lemma 2.6, for any $y \in \mathbb{R}^n$,

$$\psi^*(y) = \sup_{x \in \text{Dom}(\psi)} [\langle x, y \rangle - \psi(x)] \geq \sup_{x \in \mathbb{R}^n, |x| < c} [\langle x, y \rangle + \alpha/2] = \frac{\alpha}{2} + c|y|.$$

Since $\inf \psi = -\alpha$, we deduce that

$$\begin{aligned} \mathcal{I}_{\mu,p}(\psi) &= \int_{\mathbb{R}^n} \psi d\mu + \left(\int_{\mathbb{R}^n} \frac{dy}{(\psi^*(y))^{n+p}} \right)^{-2/p} \geq -\alpha + \left(\int_{\mathbb{R}^n} \frac{dy}{(\alpha/2 + c|y|)^{n+p}} \right)^{-2/p} \\ &= -\alpha + \alpha^2 \left(\int_{\mathbb{R}^n} \frac{dy}{(1/2 + c|y|)^{n+p}} \right)^{-2/p} = -\alpha + \tilde{c}\alpha^2. \end{aligned} \quad \square$$

Lemma 2.8. *Assume that $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a μ -integrable, convex function. Then $\text{Dom}(\psi)$ contains the interior of $\text{Conv}(\text{Supp}(\mu))$. In particular, $\text{Dom}(\psi)$ contains the origin in its interior.*

Proof. Otherwise, we could use a hyperplane and separate the convex set $\text{Dom}(\psi)$ from an open ball intersecting $\text{Supp}(\mu)$. This would imply that ψ is not μ -integrable, in contradiction. \square

Proof of Proposition 2.4. Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a proper, convex function with $\psi(0) < 0$ that is μ -integrable. We will show that

$$\mathcal{I}_{\mu,p}(\psi) \geq -\frac{1}{4\tilde{c}} \quad (9)$$

where $\tilde{c} > 0$ is the constant from Lemma 2.7. In the case where $\int \psi d\mu \geq 0$ we have $\mathcal{I}_{\mu,p}(\psi) \geq 0$, and (9) trivially holds. We may thus assume that

$$\int_{\mathbb{R}^n} \psi d\mu < 0. \quad (10)$$

The origin is in the interior of $\text{Dom}(\psi)$, according to Lemma 2.8. From Rockafellar [26, Theorem 23.4] we learn that there exists $w \in \mathbb{R}^n$ such that

$$\psi(x) \geq \psi(0) + \langle x, w \rangle \quad (x \in \mathbb{R}^n). \quad (11)$$

Recall that $\mathcal{I}_{\mu,p}(\psi) = \mathcal{I}_{\mu,p}(\psi_1)$ whenever $\psi_1(x) = \psi(x) + \langle x, v \rangle$ for some $v \in \mathbb{R}^n$. By adding an appropriate linear functional to ψ , we may assume that $w = 0$ in (11) and hence $\psi(0) = \inf \psi$.

Denote $\alpha = -\psi(0)$, which is a positive number, as follows from (10). We may now apply Lemma 2.7 and obtain that

$$\mathcal{I}_{\mu,p}(\psi) \geq -\alpha + \tilde{c}\alpha^2 \geq -\frac{1}{4\tilde{c}},$$

completing the proof of (9). The proposition is thus proven. \square

The next proposition is the second step in the proof of Theorem 2.3.

Proposition 2.9. *The infimum in Proposition 2.4 is attained.*

Again, the proof of Proposition 2.9 relies on a few small lemmas.

Lemma 2.10. *There exists a μ -integrable, proper convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$ such that $\mathcal{I}_{\mu,p}(\psi) < 0$.*

Proof. Let $\delta > 0$ and denote $\psi_\delta(x) = -\delta + \varepsilon|x|$ for $\varepsilon = \delta^{1+p/(4n)}$. Then,

$$\left(\int_{\mathbb{R}^n} \frac{dx}{(\psi_\delta^*(x))^{n+p}} \right)^{-2/p} = \left(\int_{B(0,\varepsilon)} \frac{dx}{\delta^{n+p}} \right)^{-2/p} = A\delta^{3/2}$$

where $B(0, \varepsilon) = \{x \in \mathbb{R}^n; |x| < \varepsilon\}$ and $A = \text{Vol}_n(B(0, 1))^{-2/p} > 0$. Consequently,

$$\mathcal{I}_{\mu,p}(\psi_\delta) = A\delta^{3/2} + \int_{\mathbb{R}^n} (-\delta + \varepsilon|x|)d\mu(x) = A\delta^{3/2} - \delta + \delta^{1+p/(4n)} \cdot \int_{\mathbb{R}^n} |x|d\mu(x).$$

By our assumptions on the measure μ , we know that $\int |x|d\mu(x) < \infty$. For a small, positive δ , the leading term in $\mathcal{I}_{\mu,p}(\psi_\delta)$ is $-\delta$. Consequently, $\mathcal{I}_{\mu,p}(\psi_\delta) < 0$ for a sufficiently small $\delta > 0$. \square

In order to prove Proposition 2.9, we select a minimizing sequence

$$\{\psi_\ell\}_{\ell=1,2,\dots,\infty}.$$

In other words, for any $\ell \geq 1$ the function $\psi_\ell : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a μ -integrable, proper, convex function with $\psi_\ell(0) < 0$ and

$$\mathcal{I}_{\mu,p}(\psi_\ell) \xrightarrow{\ell \rightarrow \infty} \inf_{\psi} \mathcal{I}_{\mu,p}(\psi)$$

where the infimum runs over all μ -integrable, proper, convex functions $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi(0) < 0$. Thanks to Lemma 2.10, we may select the sequence $\{\psi_\ell\}$ so that

$$\sup_{\ell \geq 1} \mathcal{I}_{\mu,p}(\psi_\ell) < 0. \quad (12)$$

Moreover, we know that $\mathcal{I}_{\mu,p}(\psi_\ell)$ remains intact when we add a linear functional to ψ_ℓ . Arguing as in the proof of Proposition 2.4, we may add appropriate linear functionals to ψ_ℓ and assume that

$$\inf_{x \in \mathbb{R}^n} \psi_\ell(x) = \psi_\ell(0) \quad \text{for } \ell \geq 1. \quad (13)$$

Lemma 2.11. *We have that $\sup_\ell \psi_\ell(0) < 0$ and $\inf_\ell \psi_\ell(0) > -\infty$.*

Proof. By (13), for any $\ell \geq 1$,

$$\psi_\ell(0) = \inf_{x \in \mathbb{R}^n} \psi_\ell(x) \leq \int_{\mathbb{R}^n} \psi_\ell d\mu \leq \mathcal{I}_{\mu,p}(\psi_\ell).$$

Inequality (12) thus implies that $\sup_\ell \psi_\ell(0) < 0$. Moreover, it follows from (12) that $\int \psi_\ell d\mu < 0$ for all ℓ . From (12), (13) and Lemma 2.7,

$$\psi_\ell(0) + \tilde{c}(\psi_\ell(0))^2 \leq \mathcal{I}_{\mu,p}(\psi_\ell) < 0 \quad (\ell \geq 1).$$

Hence $\inf_\ell \psi_\ell(0) \geq -1/\tilde{c} > -\infty$. □

Write $K \subseteq \mathbb{R}^n$ for the interior of $\text{Conv}(\text{Supp}(\mu))$. Then K is an open, convex set containing the origin. Lemma 16 in [12] states that for any non-negative, μ -integrable, convex function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ and any point $x \in K$,

$$f(x) \leq C_\mu(x) \int_{\mathbb{R}^n} f d\mu, \quad (14)$$

where $C_\mu(x) > 0$ depends solely on x and μ .

Lemma 2.12. *There exists a sequence of integers $\{\ell_j\}_{j=1,2,\dots}$ such that ψ_{ℓ_j} converges pointwise in K to a certain convex function $\psi : K \rightarrow \mathbb{R}$.*

Proof. Fix a point $x_0 \in K$. We claim that

$$\sup_{\ell \geq 1} |\psi_\ell(x_0)| < +\infty. \quad (15)$$

Indeed, the fact that the sequence $\{\psi_\ell(x_0)\}_{\ell=1,2,\dots}$ is bounded from below follows from (13) and Lemma 2.11. In order to show that this sequence is bounded from above, we denote

$$\beta = -\inf \{\psi_\ell(x) ; x \in \mathbb{R}^n, \ell \geq 1\} = -\inf \{\psi_\ell(0) ; \ell \geq 1\} \quad (16)$$

which is a finite, positive number thanks to Lemma 2.11. Apply (14) for the non-negative, μ -integrable, convex function $f_\ell = \psi_\ell + \beta$, and obtain

$$\begin{aligned} f_\ell(x_0) &\leq C_\mu(x_0) \int_{\mathbb{R}^n} f_\ell(x) d\mu(x) = C_\mu(x_0) \int_{\mathbb{R}^n} (\psi_\ell + \beta) d\mu \\ &\leq C_\mu(x_0) (\beta + \mathcal{I}_{\mu,p}(\psi_\ell)) \leq C_\mu(x_0) \beta, \end{aligned}$$

where we used (12) in the last passage. This shows that $\sup_\ell f_\ell(x_0) < \infty$, and consequently $\sup_\ell \psi_\ell(x_0) < \infty$. The proof of (15) is complete. We may now invoke Theorem 10.9 from Rockafellar [26], thanks to (15), and conclude that there exists a subsequence $\{\psi_{\ell_j}\}$ satisfying the conclusion of the lemma. □

Proof of Proposition 2.9. We will use the convergent subsequence $\{\psi_{\ell_j}\}$ from Lemma 2.12. The function $\psi = \lim_j \psi_{\ell_j}$ is finite and convex in the open, convex set K . Moreover, $\psi(0) \in (-\infty, 0)$ as follows from Lemma 2.11. Since $\psi_\ell(x) \geq \psi_\ell(0)$ for any $x \in \mathbb{R}^n$ and $\ell \geq 1$, also

$$\psi(0) = \inf_{x \in K} \psi(x) \in (-\infty, 0). \quad (17)$$

The function ψ is currently defined only in the set K . In order to have a globally defined function in \mathbb{R}^n , we set $\psi(x) = +\infty$ for $x \in \mathbb{R}^n \setminus \overline{K}$. For $x \in \partial K$, define

$$\psi(x) = \lim_{t \rightarrow 1^-} \psi(tx). \quad (18)$$

Since ψ is convex in K , it follows from (17) that the function $t \mapsto \psi(tx)$ is non-decreasing in $t \in (0, 1)$, hence the limit in (18) is well-defined. Moreover, the function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a proper, convex function, since on \overline{K} we have $\psi = \sup_{t \in (0,1)} f_t$ where $f_t(x) = \psi(tx)$ is finite, convex and continuous on \overline{K} . The measure μ is supported in the closure \overline{K} . From the pointwise convergence in K , it follows that $\psi_{\ell_j}(tx) \rightarrow \psi(tx)$ for any $0 < t < 1$ and $x \in \overline{K}$. We claim that by Fatou's lemma, for any $0 < t < 1$,

$$\int_{\overline{K}} \psi(tx) d\mu(x) \leq \liminf_{j \rightarrow \infty} \int_{\overline{K}} \psi_{\ell_j}(tx) d\mu(x) \leq \liminf_{j \rightarrow \infty} \int_{\overline{K}} \psi_{\ell_j}(x) d\mu(x). \quad (19)$$

Indeed, the use of Fatou's lemma is legitimate according to (13) and Lemma 2.11, because $\inf_{x \in \overline{K}} \psi_\ell(x) > -\infty$. The relation (13) also implies that $\psi_\ell(tx) \leq \psi_\ell(x)$ for any $x \in \overline{K}$, $\ell \geq 1$ and $0 < t < 1$, completing the justification of (19). Next, we use the fact that $\psi(tx) \nearrow \psi(x)$ as $t \rightarrow 1^-$ for any $x \in \overline{K}$. Since ψ is bounded from below, we may use the monotone convergence theorem, and upgrade (19) to the bound

$$\int_{\mathbb{R}^n} \psi d\mu = \int_{\overline{K}} \psi d\mu = \lim_{t \rightarrow 1^-} \int_{\overline{K}} \psi(tx) d\mu(x) \leq \liminf_{j \rightarrow \infty} \int_{\overline{K}} \psi_{\ell_j} d\mu = \liminf_{j \rightarrow \infty} \int_{\mathbb{R}^n} \psi_{\ell_j} d\mu. \quad (20)$$

Recall from (12) that $\sup_j \int \psi_{\ell_j} d\mu < 0$. It follows from (17) and (20) that ψ is a μ -integrable, proper, convex function with $\psi(0) < 0$. All that remains is to prove that

$$\mathcal{I}_{\mu,p}(\psi) \leq \liminf_{j \rightarrow \infty} \mathcal{I}_{\mu,p}(\psi_{\ell_j}). \quad (21)$$

The convex function ψ satisfies $K \subseteq \text{Dom}(\psi) \subseteq \overline{K}$, and $\psi_{\ell_j} \rightarrow \psi$ pointwise in K as $j \rightarrow \infty$. From Lemma 2.2,

$$\mathcal{I}_p(\psi) \leq \liminf_{j \rightarrow \infty} \mathcal{I}_p(\psi_{\ell_j}) \quad \text{and hence} \quad \mathcal{I}_p^2(\psi) \leq \liminf_{j \rightarrow \infty} \mathcal{I}_p^2(\psi_{\ell_j}). \quad (22)$$

Now (21) follows from (20), (22) and the definition of $\mathcal{I}_{\mu,p}$. \square

From the proof of Proposition 2.9 we see that the minimizer ψ may be selected so that $\psi(x) = +\infty$ for any $x \in \mathbb{R}^n \setminus \overline{K}$. Theorem 2.3 now follows from Proposition 2.4, Proposition 2.9 and Lemma 2.10.

3 q -moment measures

Let $q > 0$ and let $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ be a positive, convex function such that $Z_\varphi := \int_{\mathbb{R}^n} \varphi^{-(n+q)} < \infty$. The function φ is differentiable almost everywhere in \mathbb{R}^n because it is convex. We define the q -moment measure of φ to be the push-forward of the probability measure on \mathbb{R}^n with density $Z_\varphi^{-1}/\varphi^{n+q}$ under the measurable map $x \mapsto \nabla\varphi(x)$. In other words, a Borel probability measure μ on \mathbb{R}^n is the q -moment measure of φ if for any bounded, continuous function $b : \mathbb{R}^n \rightarrow \mathbb{R}$,

$$\int_{\mathbb{R}^n} b(y) d\mu(y) = \int_{\mathbb{R}^n} \frac{b(\nabla\varphi(x))}{\varphi^{n+q}(x)} \frac{dx}{Z_\varphi}. \quad (1)$$

The moment measure of φ is a well-defined probability measure on \mathbb{R}^n , whenever φ is a positive, convex function on \mathbb{R}^n such that $\varphi^{-(n+q)}$ is integrable.

Lemma 3.1. *Let $q > 0$ and let $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ be a positive, convex function. Then the function $\varphi^{-(n+q)}$ is integrable if and only if $\lim_{|x| \rightarrow \infty} \varphi(x) = +\infty$. Moreover, in this case there exist $\alpha, \beta > 0$ such that $\varphi(x) \geq \alpha + \beta|x|$ for all $x \in \mathbb{R}^n$.*

Proof. Assume that $\varphi^{-(n+q)}$ is integrable. Then for any $R > 0$, the open convex set $\{x \in \mathbb{R}^n; \varphi(x) < R\}$ has a finite volume and hence it is bounded. Therefore $\lim_{|x| \rightarrow \infty} \varphi(x) = +\infty$. Conversely, assume that $\varphi(x)$ tends to infinity as $|x| \rightarrow \infty$. Then there exists $R > 0$ such that $\varphi(x) \geq \varphi(0) + 1$ whenever $|x| \geq R$. By convexity, for any $|x| > R$,

$$\varphi(0) + 1 \leq \varphi\left(\frac{R}{|x|}x\right) \leq \left(1 - \frac{R}{|x|}\right)\varphi(0) + \frac{R}{|x|}\varphi(x).$$

Therefore $\varphi(x) \geq \varphi(0) + |x|/R$ for all $|x| > R$. By continuity, $c = \min_{|x| \leq R} \varphi(x)$ is positive. Hence $\varphi(x) \geq c/2 + \min\{1/R, c/(2R)\} \cdot |x|$ for all $x \in \mathbb{R}^n$, and $\varphi^{-(n+q)}$ is integrable. \square

Lemma 3.1 demonstrates that if $\varphi^{-(n+q)}$ is integrable for some $q > 0$, then it is integrable for all $q > 0$. The moment measures from [12] correspond in a sense to the case $q = \infty$, since in [12] we push forward the measure on \mathbb{R}^n with density $\exp(-\varphi)$ via the map $x \mapsto \nabla\varphi(x)$. For a convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ and for $\lambda > 0$ we say that

$$(\lambda \times \varphi)(x) = \lambda\varphi(x/\lambda) \quad (x \in \mathbb{R}^n)$$

is the λ -dilation of φ . Note that the q -moment measure of φ is exactly the same as the q -moment measure of its dilation $\lambda \times \varphi$, assuming that one of these q -moment measures exists. It is also clear that replacing $\varphi(x)$ by its translation $\varphi(x - x_0)$, for some $x_0 \in \mathbb{R}^n$, does not have any effect on the resulting q -moment measure.

Theorem 3.2. *Let $q > 1$ and let μ be a compactly-supported Borel probability measure on \mathbb{R}^n whose barycenter lies at the origin. Assume that the origin is in the interior of $\text{Conv}(\text{Supp}(\mu))$.*

Then there exists a positive, convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ whose q -moment measure is μ . This convex function φ is uniquely determined up to translation and dilation.

Theorem 3.2 is a variant for q -moment measures of a result proven in [12] in the case of moment measures. The case where μ is not compactly-supported will not be discussed in this paper, although we expect that similarly to [12], essential-continuity will play a role in the analysis of this case. We also restrict our attention to the case $q > 1$. The necessity of the barycenter condition in Theorem 3.2 follows from:

Proposition 3.3. *Let $q > 1$ and let μ be a compactly-supported Borel probability measure on \mathbb{R}^n . Assume that μ is the q -moment measure of a positive, convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$. Then the barycenter of μ lies at the origin, which belongs to the interior of $\text{Conv}(\text{Supp}(\mu))$.*

Proof. We may substitute $b(x) = x_i$ in (1), since b is bounded on $\text{Supp}(\mu)$. This shows that for $i = 1, \dots, n$,

$$\int_{\mathbb{R}^n} x_i d\mu(x) = \int_{\mathbb{R}^n} \frac{\partial_i \varphi}{\varphi^{n+q}} = -\frac{1}{n+q-1} \int_{\mathbb{R}^n} \partial_i \left(\frac{1}{\varphi^{n+q-1}} \right) = 0,$$

along the lines of [12, Lemma 4]. Therefore the barycenter of μ lies at the origin. Assume by contradiction that the origin is not in the interior of $\text{Conv}(\text{Supp}(\mu))$. Since the barycenter of μ lies at the origin, necessarily μ is supported in a hyperplane of the form $H = \theta^\perp$ for some $\theta \in S^{n-1}$. Since μ is the q -moment measure of φ , we see that

$$\partial_\theta \varphi(x) = \langle \nabla \varphi(x), \theta \rangle = 0 \quad \text{for almost all } x \in \mathbb{R}^n. \quad (2)$$

The function φ is locally-Lipschitz in \mathbb{R}^n , being a finite, convex function. The relation (2) shows that φ is constant on almost any line parallel to θ , contradicting the integrability of $\varphi^{-(n+q)}$. \square

The proof of Theorem 3.2 occupies most of the remainder of this section. Begin the proof with the following:

Lemma 3.4. *Let $q > 1$ and let $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ be a positive, convex function with $\int_{\mathbb{R}^n} \varphi^{-(n+q)} < \infty$. Write μ for the q -moment measure of φ , and assume that μ is compactly-supported. Set $\psi = \varphi^*$. Then,*

$$\int_{\mathbb{R}^n} |\psi| d\mu < \infty.$$

Proof. It follows from the definition of the Legendre transform that for any point $x \in \mathbb{R}^n$ in which φ is differentiable,

$$\langle x, \nabla \varphi(x) \rangle = \psi(\nabla \varphi(x)) + \varphi(x).$$

For almost any $x \in \mathbb{R}^n$ we have that $\nabla \varphi(x) \in \text{Supp}(\mu)$. Since μ is compactly-supported, then $|\nabla \varphi(x)|$ is an L^∞ -function in \mathbb{R}^n . Consequently,

$$\int_{\mathbb{R}^n} \varphi^{-(n+q)} \int_{\mathbb{R}^n} |\psi| d\mu = \int_{\mathbb{R}^n} \frac{|\psi(\nabla \varphi(x))|}{\varphi^{n+q}(x)} dx \leq \int_{\mathbb{R}^n} \frac{|\langle x, \nabla \varphi(x) \rangle| + \varphi(x)}{\varphi^{n+q}(x)} dx < \infty,$$

by Lemma 3.1, since $q > 1$. This completes the proof. \square

Lemma 3.5. *Let $A, p > 0$ and let μ be as in Theorem 3.2. Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a μ -integrable, proper, convex function such that $\text{Dom}(\psi)$ is bounded. For $t \in \mathbb{R}$ denote $\psi_t = \psi + t$ and $\varphi_t = \psi_t^*$. Then for any $t < -\psi(0)$, the function $\varphi_t : \mathbb{R}^n \rightarrow \mathbb{R}$ is a positive, convex function with $\int_{\mathbb{R}^n} \varphi_t^{-(n+p)} \in (0, \infty)$. Moreover, there exists $t < -\psi(0)$ with*

$$\int_{\mathbb{R}^n} \varphi_t^{-(n+p)}(x) dx = A.$$

Proof. The set $\text{Dom}(\psi)$ is assumed to be bounded. Set $L = 1 + \sup_{x \in \text{Dom}(\psi)} |x| < \infty$. Denoting $\varphi = \psi^*$, we learn from Corollary 13.3.3 in Rockafellar [26] that the convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is an L -Lipschitz function. Lemma 2.8 implies that ψ is finite in an open neighborhood of the origin. Fix $t < -\psi(0)$. By the continuity of ψ near the origin, there exists $\varepsilon_t > 0$, depending on ψ and t , such that

$$\psi_t(x) < -\varepsilon_t \quad \text{when } |x| < \varepsilon_t.$$

Hence, for any $y \in \mathbb{R}^n$ and $t < -\psi(0)$,

$$\varphi_t(y) = \sup_{x \in \text{Dom}(\psi_t)} [\langle x, y \rangle - \psi_t(x)] \geq \sup_{|x| < \varepsilon_t} [\langle x, y \rangle + \varepsilon_t] = \varepsilon_t + \varepsilon_t |y|. \quad (3)$$

Set $t_0 = -\psi(0)$, and for $t \in (-\infty, t_0)$ define

$$I(t) = \int_{\mathbb{R}^n} \frac{dx}{(\varphi_t(x))^{n+p}} = \int_{\mathbb{R}^n} \frac{dx}{(\varphi(x) - t)^{n+p}}. \quad (4)$$

It follows from (3) that the function $\varphi_t^{-(n+p)}$ is integrable on \mathbb{R}^n . The positive function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is L -Lipschitz, hence the integral of $\varphi_t^{-(n+p)}$ is positive. The function I is clearly non-decreasing in $t \in (-\infty, t_0)$, and by the monotone convergence theorem, I is continuous in $(-\infty, t_0)$. In order to conclude the lemma by the mean value theorem, it suffices to prove that

$$\lim_{t \rightarrow -\infty} I(t) = 0, \quad \lim_{t \rightarrow t_0^-} I(t) = +\infty.$$

The fact that $I(t) \rightarrow 0$ as $t \rightarrow -\infty$ is evident from (4) and the monotone convergence theorem. It remains to show that $I(t) \rightarrow +\infty$ as $t \rightarrow t_0^-$. With any $t < t_0$ we associate a point $x_0(t) \in \mathbb{R}^n$ that satisfies

$$\varphi(x_0(t)) < \frac{t_0 - t}{2} + \inf_{x \in \mathbb{R}^n} \varphi(x) = \frac{t_0 - t}{2} - \psi(0) = \frac{t_0 - t}{2} + t_0.$$

For any $t < t_0$, denoting $r = (t_0 - t)/(2L)$, we see that $\varphi(x) \leq \varphi(x_0(t)) + (t_0 - t)/2$ for any x in the ball $B(x_0(t), r)$. Therefore, for any $t < t_0$,

$$I(t) = \int_{\mathbb{R}^n} \frac{dx}{(\varphi(x) - t)^{n+p}} \geq \int_{B(x_0(t), r)} \frac{dx}{(\varphi(x) - t)^{n+p}} \geq \frac{\kappa_n r^n}{(2t_0 - 2t)^{n+p}} = \frac{\kappa_n 2^{-2n-p} L^{-n}}{(t_0 - t)^p}$$

where $\kappa_n = \text{Vol}_n(B(0, 1))$ is the volume of the Euclidean unit ball. Since $p > 0$,

$$\lim_{t \rightarrow t_0^-} I(t) \geq \lim_{t \rightarrow t_0^-} \frac{\kappa_n 2^{-2n-p} L^{-n}}{(t_0 - t)^p} = +\infty$$

and the lemma is proven. \square

Lemma 3.6. *Let $q > 1$ and let μ be as in Theorem 3.2. Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be the μ -integrable, proper, convex function whose existence is guaranteed by Theorem 2.3 with $p = q - 1$.*

Denote $\varphi = \psi^$. Then $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is a positive function and the probability measure ν on \mathbb{R}^n with density $Z_\varphi^{-1}/\varphi^{n+q}$ is well-defined. Moreover, for any function $\psi_1 : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ of the form $\psi_1 = \psi + b$, with $b : \mathbb{R}^n \rightarrow \mathbb{R}$ being a bounded function, we have*

$$\int_{\mathbb{R}^n} \psi d\mu + \int_{\mathbb{R}^n} \psi^* d\nu \leq \int_{\mathbb{R}^n} \psi_1 d\mu + \int_{\mathbb{R}^n} \psi_1^* d\nu. \quad (5)$$

Proof. Write \overline{K} for the closure of $\text{Conv}(\text{Supp}(\mu))$, a compact set in \mathbb{R}^n . Theorem 2.3 states that $\psi(0) < 0$ and that $\text{Dom}(\psi) \subseteq \overline{K}$. Therefore, by Lemma 3.5, the function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is a positive, convex function with

$$\int_{\mathbb{R}^n} \varphi^{-(n+p)} \in (0, +\infty). \quad (6)$$

It thus follows from Lemma 3.1 that the probability measure ν is well-defined. The function ψ_1^{**} is proper, convex, and it satisfies $\psi - C \leq \psi_1^{**} \leq \psi_1 \leq \psi + C$ for some $C > 0$. It suffices to prove (5) under the additional assumption that ψ_1 is proper and convex: Otherwise, replace ψ_1 with the smaller ψ_1^{**} , and observe that the right-hand side of (5) cannot increase under such a replacement.

Hence we may assume that ψ_1 is a μ -integrable, proper, convex function. Moreover, the convex set $\text{Dom}(\psi_1) = \text{Dom}(\psi)$ is bounded according to Theorem 2.3. The right hand-side of (5) is not altered if we add a constant to the function ψ_1 , since μ and ν are probability measures. By adding an appropriate constant to ψ_1 and by using Lemma 3.5 and (6), we may assume that the convex function ψ_1 satisfies that $\psi_1(0) < 0$ and

$$\int_{\mathbb{R}^n} \frac{dx}{\varphi_1^{n+p}(x)} = \int_{\mathbb{R}^n} \frac{dx}{\varphi^{n+p}(x)} \quad (7)$$

where $\varphi_1 = \psi_1^* : \mathbb{R}^n \rightarrow \mathbb{R}$ is a positive function. Since $\psi_1(0) < 0$, by Theorem 2.3,

$$\int_{\mathbb{R}^n} \psi d\mu + \left(\int_{\mathbb{R}^n} \frac{1}{\varphi^{n+p}} \right)^{-2/p} \leq \int_{\mathbb{R}^n} \psi_1 d\mu + \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-2/p}. \quad (8)$$

From (7) and (8),

$$\int_{\mathbb{R}^n} \psi d\mu \leq \int_{\mathbb{R}^n} \psi_1 d\mu. \quad (9)$$

Note the elementary inequality

$$\frac{n+p}{t^{n+p+1}}(t-s) \leq \frac{1}{s^{n+p}} - \frac{1}{t^{n+p}} \quad (s, t > 0)$$

which follows from the convexity of the function $t \mapsto t^{-(n+p)}$ on $(0, \infty)$. The latter inequality implies that

$$\int_{\mathbb{R}^n} (\varphi - \varphi_1) \frac{n+p}{\varphi^{n+p+1}} \leq \int_{\mathbb{R}^n} \left[\frac{1}{\varphi_1^{n+p}} - \frac{1}{\varphi^{n+p}} \right] = 0 \quad (10)$$

where we used (7) in the last passage. Since $\varphi_1 - \varphi$ is a bounded function, all integrals in (10) converge. From (10) and the definition of the measure ν ,

$$\int_{\mathbb{R}^n} \varphi d\nu \leq \int_{\mathbb{R}^n} \varphi_1 d\nu. \quad (11)$$

The desired inequality (5) follows from (9) and (11). \square

Proof of the existence part in Theorem 3.2. Lemma 3.6 is the variational problem associated with *optimal transportation*, see Brenier [7] and Gangbo and McCann [16]. Let $\psi, \varphi = \psi^*$ and ν be as in Lemma 3.6. Then $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is a positive, convex function on \mathbb{R}^n . A standard argument from [7, 16] leads us from (5) to the conclusion that $\nabla \varphi$ pushes forward the measure ν to the measure μ .

Let us provide some details. The idea of this standard argument is to apply (5) with the function $\psi_1 = \psi + \varepsilon b$, where $\varepsilon > 0$ is a small number and $b : \mathbb{R}^n \rightarrow \mathbb{R}$ is a bounded, continuous function. Denoting $\psi_\varepsilon = \psi + \varepsilon b$ for $0 \leq \varepsilon < 1$ and $\varphi_\varepsilon = \psi_\varepsilon^*$, one verifies that

$$\left. \frac{d\varphi_\varepsilon(x)}{d\varepsilon} \right|_{\varepsilon=0} = -b(\nabla \varphi(x))$$

at any point $x \in \mathbb{R}^n$ in which φ is differentiable (see, e.g., Berman and Berndtsson [3, Lemma 2.7] for a short proof). Consequently, by the bounded convergence theorem,

$$\left. \frac{d}{d\varepsilon} \left(\int_{\mathbb{R}^n} \psi_\varepsilon d\mu + \int_{\mathbb{R}^n} \varphi_\varepsilon d\nu \right) \right|_{\varepsilon=0} = \int_{\mathbb{R}^n} b(x) d\mu(x) - \int_{\mathbb{R}^n} b(\nabla \varphi(x)) d\nu(x). \quad (12)$$

However, the expression in (12) must vanish according to (5). Recalling that the density of ν is proportional to $\varphi^{-(n+q)}$, we conclude that (1) is valid for any bounded, continuous function b . Therefore μ is the q -moment measure of φ . \square

Our next inequality is analogous to Theorem 8 from [12], and may be viewed as an “above tangent” version of the Borell-Brascamp-Lieb inequality.

Proposition 3.7. *Let $q > 1$ and let μ be as in Theorem 3.2. Suppose that $\varphi_0 : \mathbb{R}^n \rightarrow (0, \infty)$ is a convex function whose q -moment measure is μ . Denote $p = q - 1$ and $\psi_0 = \varphi_0^*$. Then ψ_0 is μ -integrable, and for any μ -integrable, proper, convex function $\psi_1 : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\psi_1(0) < 0$, denoting $\varphi_1 = \psi_1^*$,*

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-2/p} \geq \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-2/p} + \frac{2(n+p) \int_{\mathbb{R}^n} \varphi_0^{-(n+p+1)}}{p \left(\int_{\mathbb{R}^n} \varphi_0^{-(n+p)} \right)^{\frac{p+2}{p}}} \int_{\mathbb{R}^n} (\psi_0 - \psi_1) d\mu.$$

We begin the proof of Proposition 3.7 with two reductions:

Lemma 3.8. *It suffices to prove Proposition 3.7 under the additional requirements that $\text{Dom}(\psi_1) \subseteq \text{Dom}(\psi_0)$ and that $\psi_1 - \psi_0$ is bounded from below on $\text{Dom}(\psi_0)$.*

Proof. It follows from Lemma 3.1 that $\psi_0(0) < 0$. For $N > 0$ and $x \in \mathbb{R}^n$ define $f_N(x) = \max\{\psi_1(x), \psi_0(x) - N\}$. The functions ψ_0 and ψ_1 are negative at zero, and hence f_N is a proper, convex function on \mathbb{R}^n with $f_N(0) < 0$ and $\text{Dom}(f_N) \subseteq \text{Dom}(\psi_0)$. The function ψ_0 is μ -integrable according to Lemma 3.4. The μ -integrability of ψ_0 and ψ_1 implies that f_N is μ -integrable. Assuming that Proposition 3.7 is proven under the additional requirement in the formulation of the lemma, we may assert that

$$\left(\int_{\mathbb{R}^n} \frac{1}{(f_N^*)^{n+p}} \right)^{-2/p} \geq \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-2/p} + \frac{2(n+p) \int_{\mathbb{R}^n} \varphi_0^{-(n+p+1)}}{p \left(\int_{\mathbb{R}^n} \varphi_0^{-(n+p)} \right)^{\frac{p+2}{p}}} \int_{\mathbb{R}^n} (\psi_0 - f_N) d\mu. \quad (13)$$

All that remains is to prove that

$$\int_{\mathbb{R}^n} \psi_1 d\mu = \lim_{N \rightarrow \infty} \int_{\mathbb{R}^n} f_N d\mu \quad (14)$$

and

$$\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \leq \liminf_{N \rightarrow \infty} \int_{\mathbb{R}^n} \frac{1}{(f_N^*)^{n+p}}. \quad (15)$$

Since $f_N \geq \psi_1$ then $f_N^* \leq \varphi_1$ and $(f_N^*)^{-(n+p)} \geq \varphi_1^{-(n+p)}$. Hence (15) holds trivially. Note that $f_N \searrow \psi_1$ as $N \rightarrow \infty$ pointwise in $\text{Dom}(\psi_0)$. Since ψ_0 is μ -integrable, the set $\text{Dom}(\psi_0)$ has a full μ -measure. Consequently, $f_N(x) \searrow \psi_1(x)$ as $N \rightarrow \infty$ for μ -almost any $x \in \mathbb{R}^n$. The monotone convergence theorem implies (14). \square

Lemma 3.9. *It suffices to prove Proposition 3.7 under the additional requirement that $\text{Dom}(\psi_1) = \text{Dom}(\psi_0)$ and that $\psi_1 - \psi_0$ is bounded on $\text{Dom}(\psi_0)$.*

Proof. According to Lemma 3.8, we may assume that for some $C > 0$,

$$\psi_1(x) + C \geq \psi_0(x) \quad (x \in \mathbb{R}^n). \quad (16)$$

It follows from (16) that for any $N > 0$,

$$\varphi_0 - N \leq \max\{\varphi_1, \varphi_0 - N\} \leq \varphi_0 + C. \quad (17)$$

For $N > 0$, let us define

$$g_N = (\max\{\varphi_1, \varphi_0 - N\})^*. \quad (18)$$

Since φ_0 is a proper, convex function, it follows from (17) that $g_N : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a proper, convex function as well. It also follows from (17) that $\text{Dom}(g_N) = \text{Dom}(\psi_0)$ and that $g_N - \psi_0$ is a bounded function on $\text{Dom}(\psi_0)$. The μ -integrability of ψ_0 , proved in Lemma 3.4, implies that g_N is μ -integrable. We learn from (18) that $g_N(0) \leq \psi_1(0) < 0$. Assuming that Proposition 3.7 is proven under the additional requirement in the formulation of this lemma, we may assert that (13) holds true when f_N is replaced by g_N . All that remains to prove is that

$$\int_{\mathbb{R}^n} \psi_1 d\mu \geq \limsup_{N \rightarrow \infty} \int_{\mathbb{R}^n} g_N d\mu \quad (19)$$

and

$$\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \leq \liminf_{N \rightarrow \infty} \int_{\mathbb{R}^n} \frac{1}{(g_N^*)^{n+p}}. \quad (20)$$

Since $\psi_1 \geq g_N$ then (19) holds trivially. Since $\text{Dom}(\varphi_0) = \mathbb{R}^n$, it follows from (18) that

$$g_N^* = \max\{\varphi_1, \varphi_0 - N\} \xrightarrow{N \rightarrow \infty} \varphi_1$$

pointwise in \mathbb{R}^n . Now (20) follows from Fatou's lemma. \square

Proof of Proposition 3.7. The μ -integrability of ψ_0 follows from Lemma 3.4, while Lemma 3.1 implies that $\inf \varphi_0 > 0$. According to Lemma 3.9, we may assume that $\text{Dom}(\psi_0) = \text{Dom}(\psi_1)$, and that

$$M = \sup_{\text{Dom}(\psi_0)} |\psi_1 - \psi_0| < \infty. \quad (21)$$

Denote $f(x) = \psi_0(x) - \psi_1(x)$ for $x \in \text{Dom}(\psi_0)$ and $f(x) = +\infty$ for $x \notin \text{Dom}(\psi_0)$. Set $\psi_t = (1-t)\psi_0 + t\psi_1$ and $\varphi_t = \psi_t^*$. Thus $\text{Dom}(\psi_t) = \text{Dom}(\psi_0)$ while $\psi_t = \psi_0 - tf$ in the set $\text{Dom}(\psi_0)$. At any point $x \in \mathbb{R}^n$ in which φ_0 is differentiable, for any $0 \leq t \leq 1$,

$$\varphi_t(x) = \psi_t^*(x) = \sup_{y \in \text{Dom}(\psi_0)} [\langle x, y \rangle - \psi_0(y) + tf(y)] \stackrel{\text{"}y=\nabla\varphi_0(x)\text{"}}{\geq} \varphi_0(x) + tf(\nabla\varphi_0(x)). \quad (22)$$

Denote $m = \inf \varphi_0$, which is a finite, positive number, thanks to the integrability of $\varphi_0^{-(n+q)}$ and to Lemma 3.1. By the Lagrange mean-value theorem from calculus, for any $a, b, t \in \mathbb{R}$ with $0 < t < m/(2M)$, $a \geq m$ and $|b| \leq M$,

$$\frac{1}{t} \left[\frac{1}{(a+tb)^{n+p}} - \frac{1}{a^{n+p}} \right] = -\frac{n+p}{\xi^{n+p+1}} b \leq -\frac{n+p}{a^{n+p+1}} b + \frac{C_{n,p,m,M}}{a^{n+p+1}} \cdot t \quad (23)$$

for some ξ between a and $a + tb$, where $C_{n,p,m,M} > 0$ depends only on n, p, m and M . It follows from (22) and (23) that for any $t \in (0, m/(2M))$,

$$\begin{aligned} \frac{1}{t} \int_{\mathbb{R}^n} \left[\frac{1}{\varphi_t^{n+p}} - \frac{1}{\varphi_0^{n+p}} \right] &\leq \frac{1}{t} \int_{\mathbb{R}^n} \left[\frac{1}{(\varphi_0(x) + tf(\nabla \varphi_0(x)))^{n+p}} - \frac{1}{\varphi_0^{n+p}(x)} \right] dx \\ &\leq -(n+p) \int_{\mathbb{R}^n} \frac{f \circ \nabla \varphi_0}{\varphi_0^{n+p+1}} + Ct \int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p+1}} \xrightarrow{t \rightarrow 0^+} -(n+p) \int_{\mathbb{R}^n} \frac{f \circ \nabla \varphi_0}{\varphi_0^{n+p+1}}, \end{aligned} \quad (24)$$

where $C = C_{n,p,m,M}$ and we used the facts that $\varphi_0^{-(n+p+1)}$ is integrable and that $f \circ \nabla \varphi_0$ is an L^∞ -function. The relation (21) implies that $|\varphi_0(x) - \varphi_1(x)| \leq M$ for all $x \in \mathbb{R}^n$. Hence $\text{Dom}(\varphi_0) = \text{Dom}(\varphi_1) = \mathbb{R}^n$. Consequently, the function

$$I(t) = \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_t^{n+p}} \right)^{-2/p} \quad (0 \leq t \leq 1)$$

satisfies $I(0), I(1) \in [0, +\infty)$. By Lemma 2.1, the function I is the square of a non-negative, convex function in the interval $[0, 1]$. Therefore I is a convex function. Consequently, the function I is finite and upper semi-continuous in $[0, 1]$, being a convex function in the interval $[0, 1]$ which is finite at the endpoints of the interval. The lower semi-continuity of I at the origin follows from (24). Hence I is continuous at the origin, and by convexity,

$$\begin{aligned} I(1) - I(0) &\geq \liminf_{t \rightarrow 0^+} \frac{I(t) - I(0)}{t} \\ &= -\frac{2}{p} \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-\frac{p+2}{p}} \cdot \limsup_{t \rightarrow 0^+} \frac{1}{t} \int_{\mathbb{R}^n} \left[\frac{1}{\varphi_t^{n+p}} - \frac{1}{\varphi_0^{n+p}} \right] \\ &\geq \frac{2(n+p)}{p} \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-\frac{p+2}{p}} \int_{\mathbb{R}^n} \frac{f \circ \nabla \varphi_0}{\varphi_0^{n+p+1}}, \end{aligned} \quad (25)$$

where we used (24) in the last passage. The proposition follows from (25) and from the definition of μ as the q -moment measure of φ_0 . \square

The proof of Proposition 3.7 looks rather different from the transportation proof of Theorem 8 in [12]. The main difference is that above we apply the Borell-Brascamp-Lieb inequality in the form of Lemma 2.1, while in [12] we essentially reprove the Prékopa theorem.

Proof of the uniqueness part in Theorem 3.2. Assume that $\varphi_0, \varphi_1 : \mathbb{R}^n \rightarrow (0, +\infty)$ are convex functions whose q -moment measure is μ . Our goal is to prove that there exist $\lambda > 0$ and $x_0 \in \mathbb{R}^n$ such that

$$\varphi_0(x) = \lambda \varphi_1(x_0 + x/\lambda) \quad \text{for } x \in \mathbb{R}^n. \quad (26)$$

By Lemma 3.1, the integrals $\int_{\mathbb{R}^n} \varphi_i^{-(n+r)}$ converge for all $r > 0$ and $i = 0, 1$, since φ_0 and φ_1 possess q -moment measures. Replacing $\varphi_0(x)$ by its dilation $(\lambda \times \varphi_0)(x) = \lambda \varphi_0(x/\lambda)$, we may assume that

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-\frac{p+2}{p}} \int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p+1}} = \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-\frac{p+2}{p}} \int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p+1}}. \quad (27)$$

Indeed, replacing φ_0 by $\lambda \times \varphi_0$ has the effect of multiplying the left-hand side of (27) by λ , hence we may select the appropriate dilation of φ_0 and assume that (27) holds true. Denote $\psi_i = \varphi_i^*$ for $i = 0, 1$ and set

$$\psi_{1/2} = (\psi_0 + \psi_1)/2.$$

It follows from Lemma 3.1 that $\inf \varphi_i > 0$ for $i = 0, 1$. Therefore $\psi_i(0) = -\inf \varphi_i < 0$ for $i = 0, 1$ and consequently $\psi_{1/2}(0) < 0$. Denote $\varphi_{1/2} = \psi_{1/2}^*$. Lemma 2.1 implies that

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_{1/2}^{n+p}} \right)^{-1/p} \leq \frac{1}{2} \left[\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-1/p} + \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-1/p} \right]. \quad (28)$$

According to Lemma 2.1(iii), when equality holds in (28), there exist $\lambda > 0$ and $x_0 \in \mathbb{R}^n$ for which (26) holds true. All that remains to show is that equality holds in (28). The functions ψ_0 and ψ_1 are μ -integrable, according to Lemma 3.4. Hence also $\psi_{1/2} = (\psi_0 + \psi_1)/2$ is μ -integrable. Denote by α the quantity in (27). Applying Proposition 3.7 for ψ_0 and $\psi_{1/2}$ we obtain

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_{1/2}^{n+p}} \right)^{-2/p} \geq \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-2/p} + \frac{2(n+p)}{p} \alpha \int_{\mathbb{R}^n} (\psi_0 - \psi_{1/2}) d\mu.$$

Applying Proposition 3.7 for ψ_1 and $\psi_{1/2}$ we obtain

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_{1/2}^{n+p}} \right)^{-2/p} \geq \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-2/p} + \frac{2(n+p)}{p} \alpha \int_{\mathbb{R}^n} (\psi_1 - \psi_{1/2}) d\mu.$$

Adding these two inequalities, and using $2\psi_{1/2} = \psi_0 + \psi_1$, we have

$$\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_{1/2}^{n+p}} \right)^{-2/p} \geq \frac{1}{2} \left[\left(\int_{\mathbb{R}^n} \frac{1}{\varphi_0^{n+p}} \right)^{-2/p} + \left(\int_{\mathbb{R}^n} \frac{1}{\varphi_1^{n+p}} \right)^{-2/p} \right]. \quad (29)$$

From (29) we deduce that equality holds in (28), because $\sqrt{(a^2 + b^2)/2} \geq (a + b)/2$ for all $a, b \geq 0$. This completes the proof. \square

For a smooth function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ we write $\nabla^2 f(x)$ for the Hessian matrix of f at the point $x \in \mathbb{R}^n$. A smooth function $f : L \rightarrow \mathbb{R}$ is *strongly-convex*, where $L \subseteq \mathbb{R}^n$ is a convex, open set, if $\nabla^2 f(x)$ is positive-definite for any $x \in L$. Suppose that $L \subseteq \mathbb{R}^n$ is a non-empty, open, bounded, convex set. We are interested in smooth, convex solutions $\varphi : \mathbb{R}^n \rightarrow (0, \infty)$ to the equation with the constraint

$$\begin{cases} \det \nabla^2 \varphi = C/\varphi^{n+2} & \text{in } \mathbb{R}^n \\ \nabla \varphi(\mathbb{R}^n) = L \end{cases} \quad (30)$$

where $C > 0$ is a positive number. Here, of course, $\nabla \varphi(\mathbb{R}^n) = \{\nabla \varphi(x); x \in \mathbb{R}^n\}$. Thanks to the regularity theory for optimal transportation developed by Caffarelli [8] and Urbas [27], Theorem 3.2 admits the following corollary:

Theorem 3.10. *Let $L \subseteq \mathbb{R}^n$ be a non-empty, open, bounded, convex set. Then there exists a smooth, positive, convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ solving (30) if and only if the barycenter of L lies at the origin. Moreover, this convex function φ is uniquely determined up to translation and dilation.*

Proof. Let μ be the uniform measure on L , normalized to be a probability measure. Assume first that the barycenter of L lies at the origin. Then the origin belongs to the interior of $\text{Supp}(\mu)$. Applying Theorem 3.2 with $q = 2$ we obtain a positive convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ whose q -moment measure is μ . That is, for any bounded, continuous function $b : L \rightarrow \mathbb{R}$,

$$\int_L b(y) dy = C_{L,\varphi} \int_{\mathbb{R}^n} \frac{b(\nabla\varphi(x))}{\varphi^{n+2}(x)} dx, \quad (31)$$

where $C_{L,\varphi} = \text{Vol}_n(L) / \int_{\mathbb{R}^n} \varphi^{-(n+2)}$. Caffarelli's regularity theory for optimal transportation (see [8] and the Appendix in [1]) implies that φ is C^∞ -smooth in \mathbb{R}^n . It follows from (31) and from the change-of-variables formula that for any $x \in \mathbb{R}^n$,

$$\det \nabla^2 \varphi(x) = \frac{C_{L,\varphi}}{\varphi^{n+2}(x)}. \quad (32)$$

In particular, the Hessian $\nabla^2 \varphi(x)$ is invertible and hence positive-definite for any $x \in \mathbb{R}^n$. Since $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is a smooth, strongly-convex function, the set $\nabla\varphi(\mathbb{R}^n)$ is convex and open, according to Theorem 26.5 in Rockafellar [26] or to Section 1.2 in Gromov [17]. From (31) we obtain that $\nabla\varphi(\mathbb{R}^n) = L$, thus φ solves (30).

Moreover, we claim that the smooth, positive, convex solution φ to (30) is uniquely determined up to translation and dilation. Indeed, any such solution φ is strongly-convex, and consequently $\nabla\varphi$ is a diffeomorphism between \mathbb{R}^n and the convex, open set $\nabla\varphi(\mathbb{R}^n) = L$. From (30) and the change-of-variables formula we thus learn that μ is the q -moment measure of φ with $q = 2$. By Theorem 3.2, the function φ is uniquely determined up to translation and dilation.

In order to prove the other direction of the theorem, assume that φ is a smooth, positive, convex solution to (30). As explained in the preceding paragraphs, μ is the q -moment measure of φ , with $q = 2$. Proposition 3.3 now shows that the barycenter of μ lies at the origin. \square

4 The affine hemisphere equations

In this section we review the partial differential equations for affinely-spherical hypersurfaces described by Tzitzéica [24, 25], Blaschke [4] and Calabi [10]. Recall from Section 1 the definition of the *affine normal line* $\ell_M(y)$ which is a line in \mathbb{R}^{n+1} passing through the point y of the smooth, connected, locally strongly-convex hypersurface $M \subset \mathbb{R}^{n+1}$. We use $y = (x, t) \in \mathbb{R}^n \times \mathbb{R}$ as coordinates in \mathbb{R}^{n+1} . For a set $L \subseteq \mathbb{R}^n$ and a function $\psi : L \rightarrow \mathbb{R}$ denote

$$\text{Graph}_L(\psi) = \{(x, \psi(x)) ; x \in L\} \subseteq \mathbb{R}^n \times \mathbb{R} = \mathbb{R}^{n+1}.$$

The affine normal line $\ell_M(y)$ depends on the third order approximation to M near y , as shown in the following lemma:

Lemma 4.1. *Let $M \subset \mathbb{R}^{n+1}$ be a smooth, connected, locally strongly-convex hypersurface. Let $L \subseteq \mathbb{R}^n$ be an open, convex set containing the origin. Assume that $U \subseteq \mathbb{R}^{n+1}$ is an open set such that*

$$M \cap U = \text{Graph}_L(\psi)$$

where $\psi : L \rightarrow \mathbb{R}$ is a smooth, strongly-convex function with $\psi(0) = 0, \nabla\psi(0) = 0$ and $\nabla^2\psi(0) = \text{Id}$. Here, Id is the identity matrix.

Then for $y_0 = (0, 0) \in M$, the line $\ell_M(y_0)$ is the line passing through the point y_0 in the direction of the vector

$$\left(-(\nabla^2\psi(0))^{-1} \cdot \nabla(\log \det \nabla^2\psi)(0), n+2 \right) \in \mathbb{R}^n \times \mathbb{R} = \mathbb{R}^{n+1}. \quad (1)$$

Proof. The vector $v = (0, 1) \in \mathbb{R}^n \times \mathbb{R}$ is pointing to the convex side of M at the point y_0 . The tangent space to M at the point y_0 is $H = T_{y_0}M = \{(x, 0) ; x \in \mathbb{R}^n\}$. For a sufficiently small $t > 0$, the section $M_t = M \cap (H + tv)$ encloses an n -dimensional convex body $\Omega_t \subset H + tv$ given by

$$\Omega_t = \{(x, t) \in \mathbb{R}^n \times \mathbb{R} ; \psi(x) \leq t\}.$$

Denote $a_{ijk} = \partial^{ijk}\psi(0) = \frac{\partial^3\psi}{\partial x_i \partial x_j \partial x_k}(0)$. By Taylor's theorem, for a sufficiently small $t > 0$,

$$\Omega_t = \left\{ (x, t) \in \mathbb{R}^n \times \mathbb{R} ; \frac{|x|^2}{2} + \frac{1}{6} \sum_{i,j,k=1}^n a_{ijk} x_i x_j x_k + O(|x|^4) \leq t \right\},$$

where $O(|x|^4)$ is an abbreviation for an expression that is bounded in absolute value by $C|x|^4$, where C depends only on M . By using the spherical-coordinates representation of Ω_t , we see that for a sufficiently small $t > 0$,

$$\frac{\Omega_{t/2}}{\sqrt{t}} = \left\{ \left(r\theta, \sqrt{t}/2 \right) ; \theta \in S^{n-1}, 0 \leq r \leq r_t(\theta) = 1 - \frac{\sum_{i,j,k=1}^n a_{ijk} \theta_i \theta_j \theta_k}{6} \sqrt{t} + O(t) \right\},$$

where $t^{-1/2} \cdot \Omega_{t/2} = \{y/\sqrt{t} ; y \in \Omega_{t/2}\}$. Consequently, the barycenter satisfies $\text{bar}(\Omega_{t/2}) = (x_t, t/2)$ for

$$x_t = \sqrt{t} \frac{n \int_{S^{n-1}} \theta r_t(\theta)^{n+1} d\theta}{(n+1) \int_{S^{n-1}} r_t(\theta)^n d\theta} = -t \cdot \frac{n}{6} \cdot \int_{S^{n-1}} \theta \left(\sum_{i,j,k=1}^n a_{ijk} \theta_i \theta_j \theta_k \right) d\sigma_{n-1}(\theta) + O(t^{3/2}),$$

where σ_{n-1} is the uniform probability measure on S^{n-1} . Let $X = (X_1, \dots, X_n)$ be a standard Gaussian random vector in \mathbb{R}^n , and recall that $\mathbb{E}X_i^2 = 1$ and $\mathbb{E}X_i^4 = 3$ for all i . For any homogenous polynomial p of degree 4 in n real variables, we know that $\mathbb{E}p(X) = n(n+2) \int_{S^{n-1}} p(\theta) d\sigma_{n-1}(\theta)$. Hence,

$$\text{bar}(\Omega_{t/2}) = \left(-t \frac{n}{6n(n+2)} \mathbb{E}X \left[\sum_{i,j,k=1}^n a_{ijk} X_i X_j X_k \right] + O(t^{3/2}), t/2 \right).$$

Consequently, the line $\ell_M(y_0)$ is in the direction of the vector

$$\left(-\mathbb{E}X \left[\sum_{i,j,k=1}^n \partial^{ijk} \psi(0) X_i X_j X_k \right], 3(n+2) \right) = (-3\nabla(\Delta\psi)(0), 3(n+2)),$$

where $\Delta\psi = \sum_{i=1}^n \partial^{ii} \psi$. Since $\nabla^2 \psi(0) = \text{Id}$, we see that $\nabla(\Delta\psi)(0) = (\nabla^2 \psi(0))^{-1} \cdot \nabla(\log \det \nabla^2 \psi)(0)$, and the lemma is proven. \square

Suppose that V is a finite-dimensional linear space over \mathbb{R} , and let $\psi : V \rightarrow \mathbb{R}$ be a smooth, strongly-convex function. In general it is impossible to identify a specific vector in V as the gradient of the function ψ at the origin, unless we introduce additional structure such as a scalar product. Nevertheless, a simple and useful observation is that the vector

$$(\nabla^2 \psi(0))^{-1} \cdot \nabla (\log \det \nabla^2 \psi)(0) \quad (2)$$

is a well-defined vector in V . This means that for any scalar product that one may introduce in V , we may compute the expression in (2) relative to this scalar product, and the result will always be the same vector in V .

Lemma 4.2. *Let $M \subset \mathbb{R}^{n+1}$ be a hypersurface and let $L \subseteq \mathbb{R}^n$ be a non-empty, open, convex set. Suppose that $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a proper, convex function whose restriction to the set L is finite, smooth and strongly convex. Denote $\Lambda(x) = \log \det \nabla^2 \psi(x)$ for $x \in L$. Assume that*

$$M = \text{Graph}_L(\psi).$$

Let $x_0 \in L$ and denote $y_0 = (x_0, \psi(x_0)) \in M$. Then the affine normal line $\ell_M(y_0) \subseteq \mathbb{R}^{n+1}$ is the line passing through the point $y_0 \in \mathbb{R}^{n+1}$ in the direction of the vector

$$\left(-(\nabla^2 \psi)^{-1} \nabla \Lambda, n+2 - \left\langle (\nabla^2 \psi)^{-1} \nabla \Lambda, \nabla \psi \right\rangle \right) \in \mathbb{R}^n \times \mathbb{R} = \mathbb{R}^{n+1}, \quad (3)$$

where all expressions are evaluated at the point x_0 .

Proof. Translating, we may assume that $x_0 = 0$ and $\psi(0) = 0$. Consider first the case where also $\nabla \psi(0) = 0$. In this case, the vector in (3) does not depend on the choice of the Euclidean structure in \mathbb{R}^n , hence we may switch to a Euclidean structure for which $\nabla^2 \psi(0) = \text{Id}$. Thus (3) follows from Lemma 4.1 in this case. In the case where $v := \nabla \psi(0)$ is a non-zero vector, we apply the linear map in \mathbb{R}^{n+1} ,

$$(x, t) \mapsto (x, t - \langle x, v \rangle).$$

This linear map transforms M to the graph of the convex function $\psi_1(x) = \psi(x) - \langle x, v \rangle$, and it transforms the vector in (3) to the vector

$$\left(-(\nabla^2 \psi_1(0))^{-1} \cdot \nabla(\log \det \nabla^2 \psi_1)(0), n+2 \right) \in \mathbb{R}^{n+1}.$$

Since $\nabla \psi_1(0) = 0$, we have reduced matters to the case already proven. \square

Remark 4.3. The affine normal lines considered in this paper are closely related to the *affine normal field* which is discussed, e.g., by Nomizu and Sasaki [20, Section II.3]. The affine normal field is a certain map $\xi : M \rightarrow \mathbb{R}^{n+1}$ that is well-defined whenever $M \subseteq \mathbb{R}^{n+1}$ is a smooth, connected, locally strongly-convex hypersurface. The relation between the affine normal field and the affine normal line is simple: For any $y \in M$, the affine normal field ξ_y is pointing in the direction of the affine normal line $\ell_M(y)$. Indeed, using affine-invariance it suffices to verify this in the case where $M = \text{Graph}_L(\psi)$. Example 3.3 in [20, Section II.3] demonstrates that when $M = \text{Graph}_L(\psi)$, for any $x \in L$ and $y = (x, \psi(x)) \in M$,

$$\xi_y = \frac{(\det \nabla^2 \psi)^{1/(n+2)}}{n+2} \cdot (-(\nabla^2 \psi)^{-1} \nabla \Lambda, n+2 - \langle (\nabla^2 \psi)^{-1} \nabla \Lambda, \nabla \psi \rangle) \in \mathbb{R}^n \times \mathbb{R}, \quad (4)$$

where $\Lambda = \log \det \nabla^2 \psi$ and all expressions involving ψ and Λ are evaluated at the point x . The vector in (4) is proportional to the vector described in Lemma 4.2, and hence ξ_y is pointing in the direction of the line $\ell_M(y)$.

Proposition 4.4. *Let M, L and ψ be as in Lemma 4.2. Denote $\varphi = \psi^*$ and $\Omega = \nabla \psi(L) = \{\nabla \psi(x) ; x \in L\}$. Then the following hold:*

- (i) *The set $\Omega \subseteq \mathbb{R}^n$ is open and the function φ is smooth in Ω .*
- (ii) *The hypersurface M is affinely-spherical with center at the origin if and only if there exists $C \in \mathbb{R} \setminus \{0\}$ such that*

$$\varphi^{n+2} \cdot \det \nabla^2 \varphi = C \quad \text{in the entire set } \Omega. \quad (5)$$

Proof. The function ψ is smooth and strongly-convex in the open, convex set L . By strong-convexity, the smooth map $\nabla \psi : L \rightarrow \Omega$ is one-to-one (see, e.g., [26, Theorem 26.5]). Moreover, the differential of the smooth map $\nabla \psi : L \rightarrow \Omega$ is non-singular, and by the inverse function theorem from calculus, the set $\Omega = \nabla \psi(L)$ is open and the map $\nabla \psi : L \rightarrow \Omega$ is a diffeomorphism. According to [26, Corollary 23.5.1], the inverse of the map $\nabla \psi$ is the smooth map $\nabla \varphi : \Omega \rightarrow L$, and hence

$$\nabla^2 \varphi = (\nabla^2 \psi)^{-1} \circ \nabla \varphi. \quad (6)$$

Thus (i) is proven. We move on to the proof of (ii). Assume first that M is affinely-spherical with center at the origin. Then for any $x \in L$, the vector in (3) is proportional to $(x, \psi(x))$. That is, for any $x \in L$,

$$-\psi(x) (\nabla^2 \psi)^{-1} \nabla (\log \det \nabla^2 \psi) = \left[n+2 - \left\langle (\nabla^2 \psi)^{-1} \nabla (\log \det \nabla^2 \psi), \nabla \psi \right\rangle \right] x. \quad (7)$$

By using the shorter Einstein notation we may rephrase (7) as follows: for $x \in L$ and $i = 1, \dots, n$,

$$-\psi \psi_k^{ik} = \left(n+2 - \psi_k^{jk} \psi_j \right) x^i. \quad (8)$$

Let us briefly explain this standard notation. We denote $x = (x^1, \dots, x^n) \in \mathbb{R}^n$, $\nabla^2 \psi(x) = (\psi_{ij}(x))_{i,j=1,\dots,n}$ and $(\nabla^2 \psi)^{-1}(x) = (\psi^{ij}(x))_{i,j=1,\dots,n}$. We abbreviate $\psi_{ij}^k = \sum_{\ell=1}^n \psi^{\ell k} \psi_{ij\ell}$ and $\psi_k^{ij} = \sum_{\ell,m=1}^n \psi^{i\ell} \psi^{jm} \psi_{\ell mk}$, where $\psi_{ijk} = \partial^{ijk} \psi$. The sums are usually implicit in the Einstein notation: an index which appears twice in an expression, once as a superscript and once as a subscript, is being summed upon from 1 to n . The Legendre transform fits well with the Einstein notation, thanks to identities such as

$$\psi^{ijk}(x) = -\varphi_{ijk}(y) \quad \text{and} \quad \psi_k^{ij}(x) = -\varphi_{ij}^k(y),$$

where expressions involving ψ are evaluated at the point $x \in L$ and expressions involving φ are evaluated at the point $y = \nabla \psi(x) \in \Omega$. Here, $(\nabla^2 \varphi)^{-1}(y) = (\varphi^{ij}(y))_{i,j=1,\dots,n}$ and $\varphi_{ij}^k = \sum_{\ell} \varphi^{\ell k} \varphi_{ij\ell}$. We may thus change variables $y = \nabla \psi(x)$, and translate (8) to the equation: for any $y \in \Omega$ and $i = 1, \dots, n$,

$$(y^j \varphi_j - \varphi) \varphi_{ik}^k = (n + 2 + \varphi_{jk}^k y^j) \varphi_i. \quad (9)$$

The function ψ is smooth and strongly convex, hence the set $\{x \in L; \psi(x) \neq 0\}$ is an open, dense set in L . Denote $U = \{y \in \Omega; \psi(\nabla \varphi(y)) \neq 0\}$, an open, dense set in Ω . For any $y \in U$ we may define

$$A(y) = \frac{n + 2 + \varphi_{jk}^k y^j}{(\sum_{\ell} y^{\ell} \varphi_{\ell}) - \varphi}.$$

Thus $\varphi_{ik}^k = A \varphi_i$ throughout the set U , according to (9). Moreover, the following holds in the set U , for $i = 1, \dots, n$:

$$y^j \varphi_j \varphi_{ik}^k = A y^j \varphi_j \varphi_i = \varphi_{jk}^k y^j \varphi_i. \quad (10)$$

From (9) and (10), we have

$$-\varphi \varphi_{ik}^k = (n + 2) \varphi_i. \quad (11)$$

The validity of (11) in the dense set $U \subseteq \Omega$ implies by continuity that (11) holds true in the entire open set Ω . By multiplying (11) by $\varphi^{n+1} \cdot \det \nabla^2 \varphi$ we obtain that in all of Ω ,

$$\nabla(\varphi^{n+2} \cdot \det \nabla^2 \varphi) = 0. \quad (12)$$

The set Ω is connected, being the image of the connected set L under a smooth map. Hence $\det \nabla^2 \varphi \cdot \varphi^{n+2} \equiv C$ in Ω . This constant C cannot be zero according to (6), because $\det \nabla^2 \varphi$ never vanishes in Ω and φ is not the zero function. This completes the verification of (5). We have thus proven one direction of (ii). However, all of our manipulations in this proof are reversible: The validity of (5) implies the validity of (11), which in turn leads to (9) and eventually to (7). Hence (5) implies that M is affinely-spherical with center at the origin. \square

The following proposition is close to the original definition of affinely-spherical hypersurfaces given by Tzitzéica [24, 25].

Proposition 4.5. *Let $M \subset \mathbb{R}^{n+1}$ be a smooth, connected, locally strongly-convex hypersurface. For $y \in M$ write $K_y > 0$ for the Gauss curvature of M at the point y and denote*

$$\rho_y = \langle y, N_y \rangle$$

where $N_y \in \mathbb{R}^{n+1}$ is the Euclidean unit normal to M at the point y , pointing to the concave side of M . Then M is affinely-spherical with center at the origin if and only if there exists $C \in \mathbb{R} \setminus \{0\}$ such that $\rho_y^{n+2}/K_y = C$ for all $y \in M$.

Proof. See Nomizu and Sasaki [20, Section II.5] for a proof of this proposition, or alternatively argue as follows: Since M is connected, it suffices to show that M is affinely-spherical with center at the origin if and only if the function $y \mapsto \rho_y^{n+2}/K_y$ is locally-constant in M and it never vanishes.

Fix $y_0 \in M$. By applying a rotation in \mathbb{R}^{n+1} , we may assume that in a neighborhood of y_0 , the hypersurface M looks like the graph of a strongly-convex function. That is, we may assume that there exist an open set $U \subseteq \mathbb{R}^{n+1}$ with $y_0 \in U$, a convex, open set $L \subseteq \mathbb{R}^n$ and a proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ which is finite, smooth and strongly-convex in L , such that

$$M \cap U = \text{Graph}_L(\psi).$$

A standard exercise in differential geometry is to show that for any $x \in L$, at the point $y = (x, \psi(x))$,

$$\rho_y = \frac{\langle x, \nabla \psi(x) \rangle - \psi(x)}{\sqrt{1 + |\nabla \psi(x)|^2}}, \quad (13)$$

and

$$K_y = \det \nabla^2 \psi(x) \cdot (1 + |\nabla \psi(x)|^2)^{-n/2-1}. \quad (14)$$

Denote $\varphi = \psi^*$. From (13) and (14) we obtain that

$$\frac{\rho_y^{n+2}}{K_y} = \frac{(\langle x, \nabla \psi(x) \rangle - \psi(x))^{n+2}}{\det \nabla^2 \psi(x)} = \varphi^{n+2}(z) \cdot \det \nabla^2 \varphi(z)$$

where $z = \nabla \psi(x)$. The desired conclusion now follows from Proposition 4.4. \square

5 The polar affinely-spherical hypersurface

In this section we prove Theorem 1.2. We begin with a variant of a construction in convexity considered by Artstein-Avidan and Milman [2] and by Rockafellar [26, Section 15]. Fix a dimension n , and denote

$$\mathcal{H}^+ = \{(x, t) \in \mathbb{R}^n \times \mathbb{R}; t > 0\} \subseteq \mathbb{R}^{n+1}, \quad \mathcal{H}^- = \{(x, t) \in \mathbb{R}^n \times \mathbb{R}; t < 0\} \subseteq \mathbb{R}^{n+1}.$$

Consider the fractional-linear transformations $I^+ : \mathcal{H}^+ \rightarrow \mathcal{H}^-$ and $I^- : \mathcal{H}^- \rightarrow \mathcal{H}^+$ defined via

$$I^+(x, t) = \left(\frac{x}{t}, -\frac{1}{t} \right), \quad I^-(y, s) = \left(-\frac{y}{s}, -\frac{1}{s} \right).$$

Then I^+ is a diffeomorphism whose inverse is I^- . A subset $V \subseteq \mathcal{H}^\pm$ is a *relative half-space* if $V = A \cap \mathcal{H}^\pm$ where $A \subseteq \mathbb{R}^{n+1}$ takes the form

$$A = \{(x, t) \in \mathbb{R}^n \times \mathbb{R}; \langle x, \theta \rangle + bt + c \geq 0\} \subseteq \mathbb{R}^{n+1}$$

for some $\theta \in \mathbb{R}^n, b, c \in \mathbb{R}$. Note that a relative half-space $V \subseteq \mathcal{H}^\pm$ is a relatively-closed subset of \mathcal{H}^\pm . We say that a relative half-space $V \subseteq \mathcal{H}^\pm$ is proper if V and $\mathcal{H}^\pm \setminus V$ are non-empty.

Lemma 5.1. *The maps I^+ and I^- transform relative half-spaces to relative half-spaces.*

Proof. Let $\theta \in \mathbb{R}^n, b, c \in \mathbb{R}$. Then for any subset $V \subseteq \mathcal{H}^+$,

$$V = \{(x, t) \in \mathcal{H}^+; \langle x, \theta \rangle + bt + c \geq 0\} \iff I^+(V) = \{(y, s) \in \mathcal{H}^-; \langle y, \theta \rangle - cs + b \geq 0\}.$$

Hence $V \subseteq \mathcal{H}^+$ is a relative half-space if and only if $I^+(V) \subseteq \mathcal{H}^-$ is a relative half-space. \square

Any relatively-closed subset $A \subseteq \mathcal{H}^\pm$ which is convex is the intersection of a family of relative half-spaces in \mathcal{H}^\pm . From Lemma 5.1 we conclude the following:

Corollary 5.2. *The maps I^+ and I^- transform relatively-closed, convex sets to relatively-closed, convex sets.*

Similarly to Rockafellar [26, Section 15], we say that the set $I^\pm(A)$ is the *obverse* of the set $A \subseteq \mathcal{H}^\pm$. See Figure 2 for an example of a convex set and its obverse. The *polar body* of a convex subset $S \subseteq \mathbb{R}^d$ is defined via

$$S^\circ = \{x \in \mathbb{R}^d; \forall y \in S, \langle x, y \rangle \leq 1\}.$$

The set S° is always convex, closed and contains the origin. If $S \subseteq \mathbb{R}^d$ is convex, closed and contains the origin, then $(S^\circ)^\circ = S$. For a subset $S \subseteq \mathbb{R}^n$ and for a function $F : S \rightarrow \mathbb{R} \cup \{+\infty\}$ we write

$$\text{Epigraph}_S(F) = \{(x, t) \in S \times \mathbb{R}; F(x) \leq t\} \subseteq \mathbb{R}^{n+1}.$$

When $S = \mathbb{R}^n$ we abbreviate $\text{Epigraph}(F) = \text{Epigraph}_{\mathbb{R}^n}(F)$. Note that a function $F : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is proper and convex if and only if $\text{Epigraph}(F)$ is convex, closed and non-empty. The obverse operation interchanges between the Legendre transform and the polarity transform:

Proposition 5.3. *Let $\varphi : \mathbb{R}^n \rightarrow (0, +\infty]$ be a proper, convex function and denote $\psi = \varphi^*$. Then,*

$$I^+(\text{Epigraph}(\varphi)) = \text{Epigraph}(\psi)^\circ \cap \mathcal{H}^-. \quad (1)$$

Moreover, if $\psi(0) < \infty$ then $\text{Epigraph}(\psi)^\circ \setminus \mathcal{H}^- = \{(x, 0); x \in \text{Dom}(\psi)^\circ\} \subseteq \mathbb{R}^n \times \mathbb{R}$.

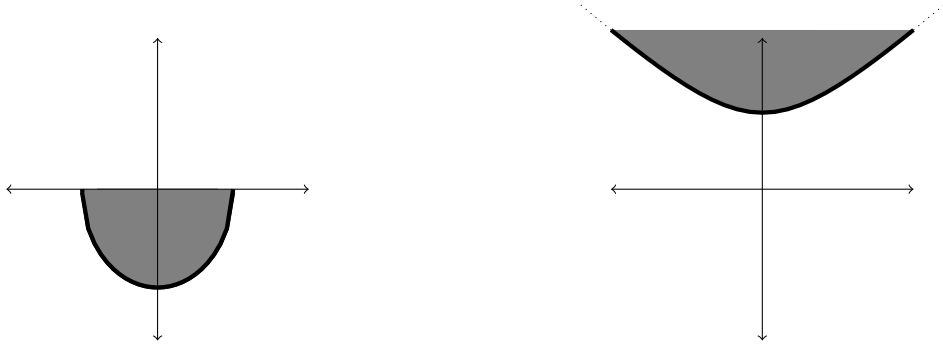


Figure 2: A semi-circle and its obverse, which is a branch of a hyperbola.

Proof. Denote $A = \text{Epigraph}(\varphi)$ and note that $A \subseteq \mathcal{H}^+$ because φ is positive. For any $(y, -s) \in \mathcal{H}^-$,

$$(y, -s) \in I^+(A) \iff (y/s, 1/s) \in A \iff \varphi(y/s) \leq 1/s. \quad (2)$$

Recall that $(s\psi)^*(y) = s\varphi(y/s)$ for any $y \in \mathbb{R}^n$ and $s > 0$. By (2), for any $(y, -s) \in \mathcal{H}^-$,

$$(y, -s) \in I^+(A) \iff (s\psi)^*(y) \leq 1 \iff \forall x \in \text{Dom}(\psi), \langle x, y \rangle - s\psi(x) \leq 1.$$

Consequently,

$$\begin{aligned} I^+(A) &= \{(y, s) \in \mathbb{R}^n \times \mathbb{R}; s < 0, \langle x, y \rangle + s\psi(y) \leq 1 \text{ for all } x \in \text{Dom}(\psi)\} \\ &= \{(y, s) \in \mathbb{R}^n \times \mathbb{R}; s < 0, \langle x, y \rangle + ts \leq 1 \text{ for all } (x, t) \in \text{Epigraph}(\psi)\}. \end{aligned} \quad (3)$$

Hence $I^+(A) = \text{Epigraph}(\psi)^\circ \cap \mathcal{H}^-$, and (1) is proven. Next, assume that $\psi(0) < \infty$. Then $\text{Epigraph}(\psi)$ contains all points of the form $(0, t)$ for $t \geq \psi(0)$. Therefore, for any $(y, s) \in \text{Epigraph}(\psi)^\circ$,

$$\langle 0, y \rangle + ts \leq 1 \quad \text{for all } t \geq \psi(0),$$

and hence $s \leq 0$. We conclude that $\text{Epigraph}(\psi)^\circ \setminus \mathcal{H}^- \subseteq \{(y, 0); y \in \mathbb{R}^n\}$. Consequently,

$$\begin{aligned} \text{Epigraph}(\psi)^\circ \setminus \mathcal{H}^- &= \{(y, 0); y \in \mathbb{R}^n, \langle x, y \rangle + t \cdot 0 \leq 1 \text{ for all } (x, t) \in \text{Epigraph}(\psi)\} \\ &= \{(y, 0); y \in \mathbb{R}^n, \langle x, y \rangle \leq 1 \text{ for all } x \in \text{Dom}(\psi)\} = \{(y, 0); y \in \text{Dom}(\psi)^\circ\}. \end{aligned} \quad \square$$

For a subset $A \subseteq \mathcal{H}^\pm \subseteq \mathbb{R}^{n+1}$ we write $\overline{A} \subseteq \mathbb{R}^{n+1}$ and $\partial A \subseteq \mathbb{R}^{n+1}$ for the usual closure and boundary of the set A , viewed as a subset of \mathbb{R}^{n+1} . Similarly, when $A \subseteq \mathcal{H}^\pm \subseteq \mathbb{R}^{n+1}$ is convex, we write A° for its polar body, where again A is viewed as a convex subset of \mathbb{R}^{n+1} . When $A \subseteq \mathcal{H}^\pm$ is relatively-closed, its closure \overline{A} is contained in \mathcal{H}^\pm , and $\overline{A} \cap \mathcal{H}^\pm = A$. Note that the relative boundary of a subset $A \subseteq \mathcal{H}^\pm$ equals $(\partial A) \cap \mathcal{H}^\pm$.

Lemma 5.4. *The two diffeomorphisms I^\pm transform smooth, connected, locally strongly-convex hypersurfaces to smooth, connected, locally strongly-convex hypersurfaces.*

Proof. Let $M \subseteq \mathcal{H}^\pm$ be a smooth, connected hypersurface. A locally-supporting relative half-space at the point $y \in M$ is a proper, relative half-space $A \subseteq \mathcal{H}^\pm$ with $y \in \partial A$ such that $A \supseteq M \cap U$ for some open neighborhood $U \subseteq \mathcal{H}^\pm$ of the point y .

A smooth, connected hypersurface $M \subseteq \mathcal{H}^\pm$ is locally strongly-convex if and only if for any $y \in M$ there is a unique locally-supporting-relative-half-space at the point y , which varies smoothly in $y \in M$ and without critical points.

The diffeomorphisms I^\pm induce a diffeomorphism between the space of proper, relative half-spaces of \mathcal{H}^+ and the space of proper, relative half-spaces of \mathcal{H}^- , as we see from the proof of Lemma 5.1. Thus, if $M \subseteq \mathcal{H}^\pm$ is a smooth, connected, locally strongly-convex hypersurface then the same holds for $I^\pm(M)$. The lemma is thus proven. \square

We say that a subset $A \subseteq \mathcal{H}^\pm$ is bounded from below if there exists $(x_0, t_0) \in \mathcal{H}^\pm$ such that

$$t > t_0 \quad \text{for all } (x, t) \in A.$$

It is easy to verify that if $A \subseteq \mathcal{H}^\pm$ is bounded from below, then its obverse is also bounded from below.

Lemma 5.5. *Let $L \subseteq \mathbb{R}^n$ be a bounded, open, convex set containing the origin. Let $B \subseteq \mathcal{H}^-$ be a relatively-closed, convex set that is bounded from below. Assume that the set $(\partial B) \cap \mathcal{H}^-$ is a smooth, connected, locally strongly-convex hypersurface, while $(\partial B) \setminus \mathcal{H}^- = \{(x, 0) ; x \in L^\circ\}$.*

Then there exists a proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\overline{\text{Dom}(\psi)} = \overline{L}$, that is smooth and strongly-convex in L , with $\nabla \psi(L) = \mathbb{R}^n$, $\psi(0) < 0$ and $\overline{B} = \text{Epigraph}(\psi)^\circ$. Moreover, $I^-(B) = \text{Epigraph}(\varphi)$ where $\varphi = \psi^$.*

Proof. Since $B \subseteq \mathcal{H}^-$, for any $(x, t) \in \mathbb{R}^n \times \mathbb{R}$ and $r > 0$,

$$(x, t) \in B^\circ \implies (x, t + r) \in B^\circ.$$

Therefore the closed set B° satisfies $B^\circ = \text{Epigraph}(\psi)$ where $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is defined via

$$\psi(x) = \inf\{t \in \mathbb{R} ; (x, t) \in B^\circ\}.$$

Here, $\inf \emptyset = +\infty$. Since $B^\circ \subseteq \mathbb{R}^{n+1}$ is closed, convex and it contains the origin, the function ψ is necessarily proper and convex. The set \overline{B} is closed, convex and it contains the origin, as follows from our assumptions. Since $\overline{B}^\circ = B^\circ = \text{Epigraph}(\psi)$ while $B \subseteq \mathcal{H}^-$ is relatively-closed,

$$\overline{B} = \text{Epigraph}(\psi)^\circ \quad \text{and} \quad B = \overline{B} \cap \mathcal{H}^- = \text{Epigraph}(\psi)^\circ \cap \mathcal{H}^-. \quad (4)$$

The set $B \subseteq \mathcal{H}^-$ is bounded from below, hence there exists $t_0 < 0$ such that $t > t_0$ for all $(x, t) \in B$. Therefore $(0, 1/t_0) \in B^\circ$ and thus $\psi(0) < 0$. Denote $\varphi = \psi^*$. Then $\varphi : \mathbb{R}^n \rightarrow (0, +\infty]$ is proper and convex. By (4) and Proposition 5.3,

$$A := I^-(B) = I^-(\text{Epigraph}(\psi)^\circ \cap \mathcal{H}^-) = \text{Epigraph}(\varphi) \quad (5)$$

and moreover,

$$(\partial B) \setminus \mathcal{H}^- = \overline{B} \setminus \mathcal{H}^- = \text{Epigraph}(\psi)^\circ \setminus \mathcal{H}^- = \{(x, 0) ; x \in \text{Dom}(\psi)^\circ\}. \quad (6)$$

However, $(\partial B) \setminus \mathcal{H}^- = \{(x, 0) ; x \in L^\circ\}$ according to our assumptions. From (6) we thus deduce that $L^\circ = \text{Dom}(\psi)^\circ$ and $\overline{L} = \overline{\text{Dom}(\psi)}$. Since $\text{Dom}(\psi) \subseteq \mathbb{R}^n$ is bounded and $\varphi = \psi^*$, necessarily

$$\text{Dom}(\varphi) = \mathbb{R}^n \quad (7)$$

by [26, Corollary 13.3.3]. The map \mathcal{I}^- is a homeomorphism, and hence it transforms the relative-boundary of $B \subseteq \mathcal{H}^-$, which is the set $(\partial B) \cap \mathcal{H}^-$, to the relative-boundary of $A \subseteq \mathcal{H}^+$, which is the set $(\partial A) \cap \mathcal{H}^+$. Since the relative-boundary $(\partial B) \cap \mathcal{H}^-$ is a smooth, connected, locally strongly-convex hypersurface, Lemma 5.4 implies that also the hypersurface

$$(\partial A) \cap \mathcal{H}^+ = \mathcal{I}^-((\partial B) \cap \mathcal{H}^-)$$

is smooth, connected and locally strongly-convex. Since $\inf \varphi = -\psi(0) > 0$, the relations (5) and (7) imply that

$$(\partial A) \cap \mathcal{H}^+ = \partial A = \text{Graph}_{\mathbb{R}^n}(\varphi).$$

Hence $\text{Graph}_{\mathbb{R}^n}(\varphi)$ is a smooth, connected, locally strongly-convex hypersurface. Consequently $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is smooth and strongly-convex. This implies that the set $\nabla \varphi(\mathbb{R}^n)$ is the interior of $\text{Dom}(\varphi^*)$ (see, e.g., [26, Theorem 26.5] or [17, Section 1.2]). We conclude that $\nabla \varphi(\mathbb{R}^n) = L$, and [26, Theorem 26.5] shows that the function $\psi = \varphi^*$ is smooth and strongly-convex in L with $\nabla \psi(L) = \mathbb{R}^n$. We have thus verified all of the conclusions of the lemma. \square

There are two convex epigraphs that are associated with the convex set $B \subseteq \mathcal{H}^-$ from Lemma 5.5: the obverse of B is $\text{Epigraph}(\varphi)$ while the polar of B is $\text{Epigraph}(\psi)$. We may think about this triplet of convex sets as three different “coordinate systems” for describing the affine hemisphere equation. We will shortly see that $\partial B \cap \mathcal{H}^-$ is an affine hemisphere centered at the origin if and only if $\text{Epigraph}_L(\psi)$ is affinely-spherical with center at the origin, which happens if and only if φ satisfies $\det \nabla^2 \varphi = C/\varphi^{n+2}$. Recall that for a smooth hypersurface $M \subseteq \mathbb{R}^{n+1}$ and $y \in M$, we view the tangent space $T_y M$ as an n -dimensional linear subspace of \mathbb{R}^{n+1} .

Definition 5.6. *Let $M \subseteq \mathbb{R}^{n+1}$ be a smooth, connected, locally strongly-convex hypersurface. Assume that $y \notin T_y M$ for all $y \in M$. For $y \in M$ define the vector $\nu_y \in \mathbb{R}^{n+1}$ via the requirements that*

$$\langle \nu_y, y \rangle = 1, \quad \nu_y \perp T_y M.$$

We refer to $\nu : M \rightarrow \mathbb{R}^{n+1}$ as the “polarity map”. We define the “polar hypersurface” M^ via*

$$M^* := \nu(M) = \{\nu_y ; y \in M\}.$$

What is the relation between polar hypersurfaces and polar bodies? If $S \subseteq \mathbb{R}^{n+1}$ is a convex set and if $M \subseteq \partial S$ is a smooth, connected, locally strongly-convex hypersurface for which the polarity map is well-defined, then $M^* \subseteq \partial S^\circ$. Thus, Definition 5.6 provides a local version of the theory of convex duality: a piece of the boundary of S is polar to a certain piece of the boundary of S° .

Suppose that $M \subseteq \mathbb{R}^{n+1}$ is a smooth, connected, locally strongly-convex hypersurface such that $y \notin T_y M$ for all $y \in M$. It is well-known that M^* is always a smooth, connected, locally strongly-convex hypersurface such that $y \notin T_y M^*$ for all $y \in M^*$. Furthermore, the polarity map $\nu : M \rightarrow M^*$ is a diffeomorphism, and its inverse is the polarity map associated with M^* . In particular, $(M^*)^* = M$.

Lemma 5.7. *Let $L \subseteq \mathbb{R}^n$ be an open, bounded, convex set containing the origin. Let $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be a proper, convex function with $\psi(0) < 0$ such that $\bar{L} = \overline{\text{Dom}(\psi)}$. Assume that ψ is smooth and strongly-convex in L with $\nabla\psi(L) = \mathbb{R}^n$. Denote*

$$M = \text{Graph}_L(\psi) \quad \text{and} \quad \tilde{K} = \text{Epigraph}(\psi)^\circ.$$

Then M^ is well-defined, the convex set \tilde{K} is compact with $\dim(\tilde{K}) = (n+1)$, and*

$$(\partial\tilde{K}) \cap \mathcal{H}^- = M^* \quad \text{while} \quad (\partial\tilde{K}) \setminus \mathcal{H}^- = \{(x, 0) ; x \in L^\circ\}. \quad (8)$$

Proof. Define $\varphi = \psi^*$. Since $\nabla\psi(L) = \mathbb{R}^n$, necessarily $\text{Dom}(\varphi) = \mathbb{R}^n$ by [26, Corollary 13.3.3]. Since $\psi(0) < 0$, the function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is positive and convex. Denote $A = \text{Epigraph}(\varphi) \subseteq \mathcal{H}^+$ and $B = \tilde{K} \cap \mathcal{H}^-$. By Proposition 5.3,

$$B = \tilde{K} \cap \mathcal{H}^- = \text{Epigraph}(\psi)^\circ \cap \mathcal{H}^- = I^+(\text{Epigraph}(\varphi)) = I^+(A). \quad (9)$$

Since $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is convex and positive, we may assert that $\partial A \cap \mathcal{H}^+ = \partial A = \text{Graph}_{\mathbb{R}^n}(\varphi)$. Consequently

$$\partial\tilde{K} \cap \mathcal{H}^- = \partial B \cap \mathcal{H}^- = I^+(\partial A \cap \mathcal{H}^+) = I^+(\text{Graph}_{\mathbb{R}^n}(\varphi)). \quad (10)$$

Since ψ is smooth in L , the identity $\psi(x) + \varphi(\nabla\psi(x)) = \langle x, \nabla\psi(x) \rangle$ holds for all $x \in L$. The fact that $\nabla\psi(L) = \mathbb{R}^n$ thus implies

$$\text{Graph}_{\mathbb{R}^n}(\varphi) = \{(\nabla\psi(x), \langle x, \nabla\psi(x) \rangle - \psi(x)) \in \mathbb{R}^n \times \mathbb{R} ; x \in L\}. \quad (11)$$

Note that $\langle x, \nabla\psi(x) \rangle - \psi(x) = \varphi(\nabla\psi(x)) > 0$ for all $x \in L$, and hence ν_y is indeed well-defined. It follows from Definition 5.6 that for $x \in L$ and $y = (x, \psi(x)) \in \text{Graph}_L(\psi)$,

$$\nu_y = \frac{(\nabla\psi(x), -1)}{\langle x, \nabla\psi(x) \rangle - \psi(x)} = I^+ \{ (\nabla\psi(x), \langle x, \nabla\psi(x) \rangle - \psi(x)) \}. \quad (12)$$

Since $M = \text{Graph}_L(\psi)$ and $M^* = \nu(M)$, by (10), (11) and (12),

$$M^* = \nu(\text{Graph}_L(\psi)) = I^+(\text{Graph}_{\mathbb{R}^n}(\varphi)) = \partial\tilde{K} \cap \mathcal{H}^-. \quad (13)$$

Proposition 5.3 shows that $\tilde{K} = \text{Epigraph}(\psi)^\circ \subseteq \overline{\mathcal{H}^-}$. In fact, according to Proposition 5.3,

$$(\partial\tilde{K}) \setminus \mathcal{H}^- = \tilde{K} \setminus \mathcal{H}^- = \{(x, 0) ; x \in \text{Dom}(\psi)^\circ\} = \{(x, 0) ; x \in L^\circ\}. \quad (14)$$

Now (8) follows from (13) and (14). It follows from (8) that $\dim(\tilde{K}) = n + 1$, since the convex set \tilde{K} affinely-spans the hyperplane $\partial\mathcal{H}^-$ while it also contains points outside this hyperplane. Moreover, since $0 \in L$ and $\psi(0) < 0$, the convex set $\text{Epigraph}(\psi)$ contains a neighborhood of the origin in \mathbb{R}^{n+1} . Therefore the closed set $\tilde{K} = \text{Epigraph}(\psi)^\circ$ is bounded, and hence it is compact. \square

Recall from Proposition 4.5 that N_y is the Euclidean unit normal to M at the point y that is pointing to the concave side of M . Recall also that we denote $\rho_y = \langle N_y, y \rangle$. It follows from Definition 5.6 that if $\rho_y \neq 0$ for all $y \in M$ then the polarity map is well-defined, and

$$\nu_y = \frac{N_y}{\rho_y} \quad \text{for all } y \in M. \quad (15)$$

The map $N : M \rightarrow S^n$ is the Gauss map associated with M , and we see that the polarity map is proportional to the Gauss map. We define the *cone measure* on a smooth hypersurface $M \subseteq \mathbb{R}^{n+1}$ to be the measure μ_M supported on M whose density with respect to the surface area measure on M is the function $y \mapsto |\rho_y|/(n+1)$. The reason for the term “cone measure” is that for any Borel subset $S \subseteq M$ that does not contain two distinct points on the same ray from the origin,

$$\mu_M(S) = \text{Vol}_{n+1}(\{tx ; 0 \leq t \leq 1, x \in S\}).$$

Proposition 5.8. *Let $M \subseteq \mathbb{R}^{n+1}$ be a smooth, connected, locally strongly-convex hypersurface. Then M is affinely-spherical with center at the origin if and only if the following holds: The polarity map $\nu : M \rightarrow M^*$ is well-defined, and it pushes forward the cone measure μ_M to a measure proportional to the cone measure μ_{M^*} .*

Proof. If M is affinely-spherical with center at the origin then the polarity map of M is well-defined, since $\rho_y \neq 0$ for all $y \in M$ according to Proposition 4.5. For $y \in M$ let $S_y : T_y M \rightarrow T_y M$ be the shape operator associated with the Euclidean unit normal N . Then $\det(S_y)$ is the Gauss curvature $K_y > 0$. For any vector field X tangent to M we have

$$D_X \nu = D_X (N/\rho) = \frac{S(X)}{\rho} - \frac{D_X \rho}{\rho^2} N, \quad (16)$$

where $D_X \nu \in \mathbb{R}^{n+1}$ is the derivative of ν in the direction of X . Write $D\nu : TM \rightarrow TM^*$ for the differential of the smooth polarity map ν . Then for any $y \in M$, the map $(D\nu)_y$ is a linear map from the tangent space $T_y \mathcal{M} = \nu_y^\perp$ to the tangent space $T_{\nu_y} M^* = y^\perp$. Here, y^\perp is the hyperplane orthogonal to y in \mathbb{R}^{n+1} . From (16), for any $y \in M$ and $u \in T_y M$,

$$S_y(u) = \rho_y \cdot \text{Proj}_{\nu_y^\perp}((D\nu)_y(u)), \quad (17)$$

where $Proj_{\nu_y^\perp}$ is the orthogonal projection operator onto ν_y^\perp in \mathbb{R}^{n+1} . The operator $Proj_{\nu_y^\perp} : y^\perp \rightarrow \nu_y^\perp$ distorts n -dimensional volumes by a factor of $|\langle y, \nu_y \rangle|/(|y||\nu_y|)$. The linear map $(D\nu)_y : \nu_y^\perp \rightarrow y^\perp$ distorts volumes by a factor of $|\det(D\nu)_y|$. Hence, by (17), for any $y \in M$,

$$K_y = \det(S_y) = |\rho_y|^n \cdot \frac{|\langle y, \nu_y \rangle|}{|y||\nu_y|} \cdot |\det(D\nu)_y| = \frac{|\det(D\nu)_y|}{|y||\nu_y|^{n+1}}, \quad (18)$$

where we used (15) in the last passage. In fact, according to (15), the cone measure μ_M has density $y \mapsto 1/((n+1)|\nu_y|)$ with respect to the surface area measure on M . Denote by θ the measure on M whose density with respect to the surface area measure is $K_y|\nu_y|^{n+1}/(n+1)$.

Recalling that the polarity map of M^* is inverse to that of M , we deduce from (18) that ν pushes forward θ to the cone measure μ_{M^*} . Consequently, ν pushes forward μ_M to a measure proportional to μ_{M^*} if and only if θ is proportional to μ_M , i.e., if and only if there exists $C > 0$ such that

$$K_y|\nu_y|^{n+1}/(n+1) = C/((n+1)|\nu_y|) \quad \text{for all } y \in M. \quad (19)$$

Recall that $1/|\nu_y| = |\rho_y|$, and that ν and ρ are continuous in the connected manifold M . By Proposition 4.5, the hypersurface M is affinely-spherical with center at the origin if and only if there exists $C > 0$ such that (19) holds true. This completes the proof. \square

Since the polarity map of M^* is the inverse to the polarity map of M , Proposition 5.8 has the following well-known corollary:

Corollary 5.9. *Let $M \subseteq \mathbb{R}^{n+1}$ be an affinely-spherical hypersurface with center at the origin. Then the polar hypersurface M^* is well-defined, and it is again affinely-spherical with center at the origin.*

Theorem 5.10. *Let $L \subseteq \mathbb{R}^n$ be an open, bounded, convex set containing the origin. Then the following are equivalent:*

- (i) *The barycenter of L lies at the origin.*
- (ii) *There exists a proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\overline{\text{Dom}(\psi)} = \overline{L}$ such that $\text{Graph}_L(\psi)$ is affinely-spherical with center at the origin, and such that ψ is smooth and strongly-convex in L with $\nabla\psi(L) = \mathbb{R}^n$ and $\psi(0) < 0$.*

Moreover, assuming (i) or (ii), the function ψ from (ii) is uniquely determined up to a multiplication by a positive scalar $\lambda > 0$ and an addition of a linear function $\ell(x) = \langle x, v \rangle$, for some $v \in \mathbb{R}^n$.

Proof. Assume (i). According to Theorem 3.10, there exists a smooth, positive, convex function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ with $\nabla\varphi(\mathbb{R}^n) = L$ such that

$$\det \nabla^2 \varphi = \frac{C}{\varphi^{n+2}} \quad \text{in } \mathbb{R}^n, \quad (20)$$

for some constant $C > 0$. Denote $\psi = \varphi^*$. From [26, Theorem 26.5] we know that $\overline{\text{Dom}(\psi)} = \overline{L}$ and that ψ is smooth and strongly convex in L with $\nabla\psi(L) = \mathbb{R}^n$. According to Proposition 4.4, equation (20) implies that $\text{Graph}_L(\psi)$ is affinely-spherical with center at the origin. The infimum of φ is attained and is positive because $0 \in L$. Hence $\psi(0) < 0$, and we have verified all conclusions in (ii).

Next, assume (ii) and let us prove (i). Denote $\varphi = \psi^*$. Since $\overline{L} = \overline{\text{Dom}(\psi)}$ is a bounded set, necessarily $\text{Dom}(\varphi) = \mathbb{R}^n$ by [26, Corollary 13.3.3]. Since ψ is smooth and strongly-convex in L with $\nabla\psi(L) = \mathbb{R}^n$ and $\psi(0) < 0$, necessarily φ is a positive, smooth, strongly-convex function in \mathbb{R}^n with $\nabla\varphi(\mathbb{R}^n) = L$. Since $\text{Graph}_L(\psi)$ is affinely-spherical with center at the origin, Proposition 4.4 shows that (20) holds true. Theorem 3.10 now implies (i). Moreover, Theorem 3.10 states that φ is uniquely determined up to translations and dilations, implying that ψ is determined up to the transformation described above. \square

Let $K \subseteq \mathbb{R}^n$ be an n -dimensional, non-empty, bounded, convex set. The *Santaló point* of K is the unique point $z(K) \in \mathbb{R}^n$ such that

$$\text{Vol}_n((K - z(K))^\circ) = \inf_{z \in \mathbb{R}^n} \text{Vol}_n(K - z)^\circ$$

where $K - z = \{x - z; x \in K\}$. The Santaló point of K is well-defined and it belongs to the interior of K , see [22, Section 7.4]. The Santaló point of K satisfies $z(K) = 0$ if and only if the barycenter of K° is well-defined and it lies at the origin. The Santaló point is affinely-invariant: for any invertible, affine transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ we know that $z(T(K)) = T(z(K))$. Hence the Santaló point is well-defined for any non-empty, bounded, convex set embedded in some finite-dimensional real linear space.

Proof of the existence part of Theorem 1.2. By applying an affine transformation in \mathbb{R}^{n+1} , we may assume that the Santaló point of K lies at the origin, and that

$$K \subseteq \{(x, 0); x \in \mathbb{R}^n\}.$$

Write $K_1 \subseteq \mathbb{R}^n$ for the interior of the set $\{x \in \mathbb{R}^n; (x, 0) \in K\}$. Then $K_1 \subseteq \mathbb{R}^n$ is an open, convex set whose Santaló point lies at the origin. Hence $K_1^\circ \subseteq \mathbb{R}^n$ is a compact, convex set containing zero in its interior such that the barycenter of K_1° lies at the origin. Write $L \subseteq \mathbb{R}^n$ for the interior of K_1° . It follows from Theorem 5.10 that there exists a proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\overline{\text{Dom}(\psi)} = \overline{L}$ such that

$$M := \text{Graph}_L(\psi)$$

is affinely-spherical with center at the origin. Moreover, $\nabla\psi(L) = \mathbb{R}^n$ and $\psi(0) < 0$. Denote

$$\tilde{K} = \text{Epigraph}(\psi)^\circ.$$

According to Corollary 5.9, the hypersurface M^* is affinely-spherical with center at the origin. Furthermore, Lemma 5.7 shows that $\tilde{K} \subseteq \mathbb{R}^{n+1}$ is an $(n+1)$ -dimensional, compact convex set and

$$M^* = (\partial\tilde{K}) \cap \mathcal{H}^- \quad \text{while} \quad (\partial\tilde{K}) \setminus \mathcal{H}^- = L^\circ \times \{0\} = K.$$

Consequently $M^* \subseteq \mathcal{H}^-$ does not intersect the hyperplane $\partial\mathcal{H}^-$ that contains K , while $\partial\tilde{K} = M^* \cup K$. According to Definition 1.1, the hypersurface M^* is an affine hemisphere with anchor K , which is centered at the Santaló point of K . \square

Proposition 5.11. *Let $L \subseteq \mathbb{R}^n$ be a bounded, open, convex set containing the origin. Let $M \subseteq \mathcal{H}^-$ be an affine hemisphere with anchor $L^\circ \times \{0\} \subseteq \mathbb{R}^n \times \mathbb{R} = \mathbb{R}^{n+1}$ and center at the origin. Then M^* is well-defined, and there exists a function ψ as in Theorem 5.10(ii) such that $M^* = \text{Graph}_L(\psi)$.*

Proof. The hypersurface $M \subseteq \mathcal{H}^-$ is an affine hemisphere with anchor $K = L^\circ \times \{0\}$ which is centered at the origin. Let \tilde{K} be as in Definition 1.1. Denote $B = \tilde{K} \cap \mathcal{H}^-$ which is a convex, relatively-closed subset of \mathcal{H}^- with $\overline{B} = \tilde{K}$. The convex set B is bounded from below in \mathcal{H}^- since \tilde{K} is compact. Moreover, by Definition 1.1 the set

$$M = (\partial\tilde{K}) \cap \mathcal{H}^- = (\partial B) \cap \mathcal{H}^- \quad (21)$$

is a smooth, connected, locally strongly-convex hypersurface. Additionally, it follows from Definition 1.1 that

$$(\partial B) \setminus \mathcal{H}^- = (\partial\tilde{K}) \setminus \mathcal{H}^- = K = L^\circ \times \{0\}. \quad (22)$$

Thus the relatively-closed, convex set $B \subseteq \mathcal{H}^-$ satisfies all of the requirements of Lemma 5.5. From the conclusion of Lemma 5.5, there exists a proper, convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ such that

$$\text{Epigraph}(\psi)^\circ = \overline{B} = \tilde{K} \quad (23)$$

and such that $\psi(0) < 0$, $\overline{\text{Dom}(\psi)} = \overline{L}$ while ψ is smooth and strongly-convex in L with $\nabla\psi(L) = \mathbb{R}^n$. Thanks to (21) and (23), Lemma 5.7 shows that

$$\text{Graph}_L(\psi) = M^*.$$

Since M is affinely-spherical with center at the origin, Corollary 5.9 implies that $\text{Graph}_L(\psi)$ is also affinely-spherical with center at the origin. Hence the function ψ satisfies all of the conditions of Theorem 5.10(ii), and the proposition is proven. \square

Proof of the uniqueness part of Theorem 1.2. Suppose that M is an affine hemisphere with anchor K , and let \tilde{K} be as in Definition 1.1. By applying an affine transformation in \mathbb{R}^{n+1} , we may assume that M is affinely-spherical with center at the origin, and that

$$K \subseteq \{(x, 0); x \in \mathbb{R}^n\} \quad \text{while} \quad \tilde{K} \subseteq \overline{\mathcal{H}^-}. \quad (24)$$

Definition 1.1 implies that the origin belongs to the relative interior of the n -dimensional, compact, convex set K . Hence there exists a bounded, open, convex set $L \subseteq \mathbb{R}^n$ containing the origin such that $K = L^\circ \times \{0\}$. From (24) and Definition 1.1 we conclude that $M = \partial\tilde{K} \cap \mathcal{H}^- \subseteq \mathcal{H}^-$. Proposition 5.11 shows that $M^* = \text{Graph}_L(\psi)$ for a certain convex function $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ satisfying the requirements of Theorem 5.10(ii).

Theorem 5.10 now implies that the barycenter of L lies at the origin, and hence the affine hemisphere M is centered at the Santaló point of K . According to Theorem 5.10, the function ψ is uniquely determined by L , up to a multiplication by a positive scalar and an addition of a linear function. It thus follows that the affine hemisphere $M = \text{Graph}_L(\psi)^*$ with anchor $L^\circ \times \{0\}$ is uniquely determined by L , up to a linear transformation. Therefore M is determined by K up to an affine transformation, and the proof is complete. \square

Remark 5.12. Let M be an affine hemisphere in \mathbb{R}^{n+1} with center at the origin and anchor $K \subseteq \mathbb{R}^n \times \{0\}$. Let $\tilde{K} \subseteq \mathbb{R}^n \times [0, \infty)$ be the convex body from Definition 1.1, so that $\partial\tilde{K} = M \cup K$. For $(x, t) \in \mathbb{R}^n \times [0, \infty)$ set

$$\|(x, t)\|_{\tilde{K}} = \inf \left\{ \lambda > 0; (x, t)/\lambda \in \tilde{K} \right\},$$

the Minkowski functional of \tilde{K} . Denote also $F(x, t) = \|(x, t)\|_{\tilde{K}}^2/2$. Since the origin belongs to the relative interior of K , the function F is a finite, 2-homogenous, convex function in the half-space $(x, t) \in \mathbb{R}^n \times [0, \infty)$. Note that the closure of the affine hemisphere M is a level set of the function F . It was noted by Bo Berndtsson that the function F satisfies

$$\begin{cases} \det \nabla^2 F(x, t) &= C & \text{for } (x, t) \in \mathbb{R}^n \times (0, \infty) \\ F(x, 0) &= \|x\|_K^2/2 & \text{for } x \in \mathbb{R}^n \end{cases} \quad (25)$$

where $C > 0$ is a positive constant and $\|x\|_K = \inf\{\lambda > 0; x/\lambda \in K\}$ is the Minkowski functional of K . Thus F solves the parabolic affine sphere equation $\det \nabla^2 F \equiv \text{Const}$ in a half-space, with boundary values that are 2-homogenous and convex. In order to prove the equation in (25), we argue as follows: The map ∇F restricted to M is precisely the polarity map of the affine hemisphere M . Since ∇F is 1-homogenous, for any measurable subset $A \subseteq M$ and $0 < \alpha < \beta$,

$$\{\nabla F(ty); y \in A, \alpha < t < \beta\} = \{tz; z \in \nu(A), \alpha < t < \beta\} \quad (26)$$

where $\nu : M \rightarrow M^*$ is the polarity map associated with M . Proposition 5.8 states that ν pushes forward the cone volume measure on M to a constant multiple of the cone volume measure on M^* . It thus follows from (26) that ∇F pushes forward the Lebesgue measure on \tilde{K} to a constant multiple of the Lebesgue measure on $\{ty; y \in M^*, t \in [0, 1]\}$. Therefore the Jacobian of the map $y \mapsto \nabla F(y)$ has a constant determinant, and (25) is proven.

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